

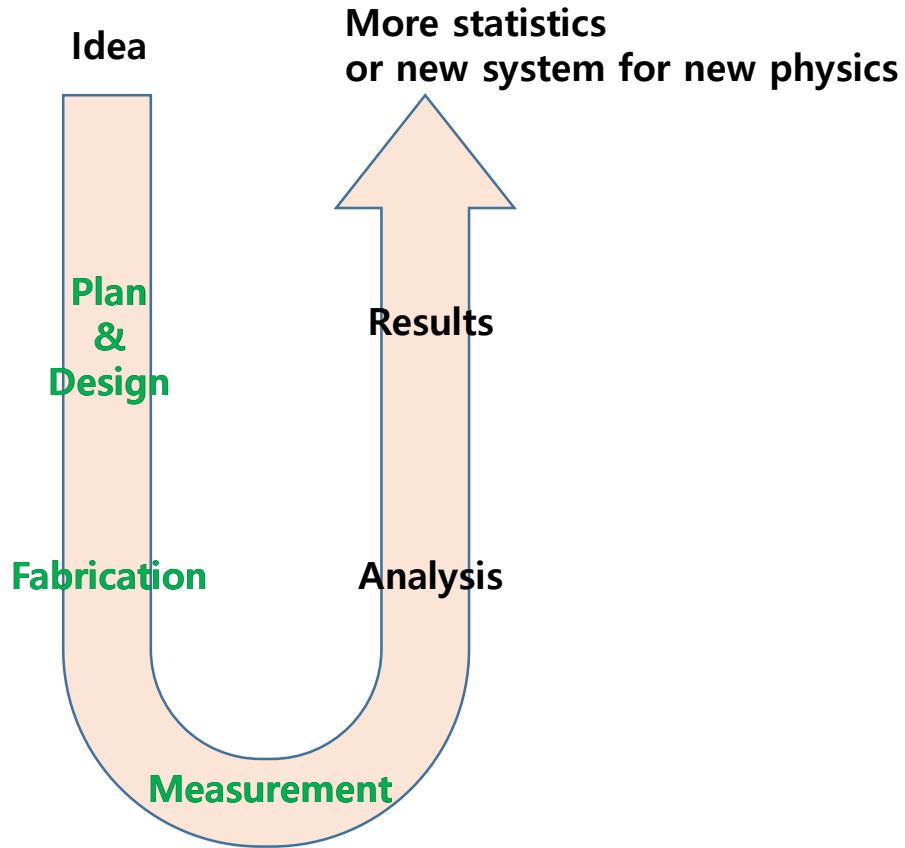
# Introduction of Fast Electronics

**RYU, Min Sang**  
**University of Seoul**

- ◆ **Role of DAQ in HEP experiment**
- ◆ **Readout scheme for DAQ**
- ◆ **Fast electronics**
  - Signal and Device impedance
  - Preamplifier
  - Fan-In and Fan-Out
  - Discriminator (LED & CFD)
  - Logic Unit for coincidence
  - TDC & ADC
- ◆ **Summary**

# Role of DAQ System in HEP experiment

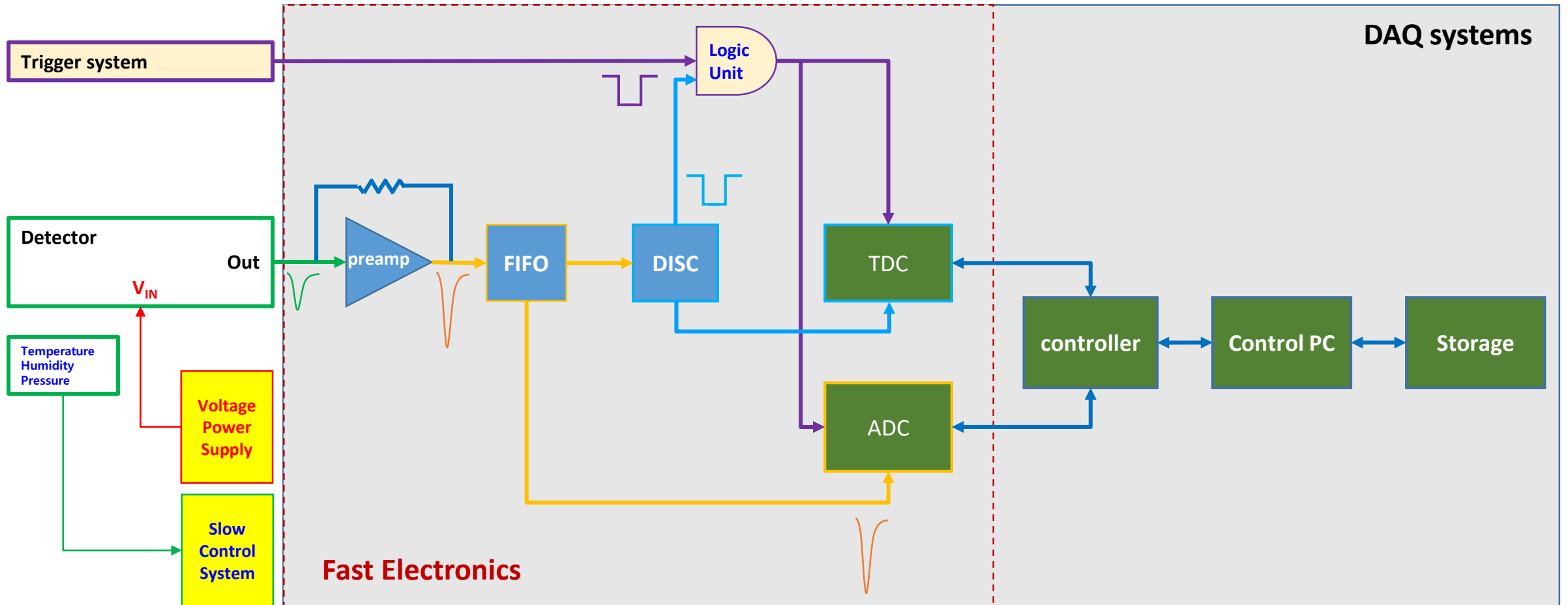
How do we watch an event in HEP experiments?



| Five Ws & Hows   | Measurement of particle detection   |
|--|---|
| <b>Why</b>   | <b>Why</b> needs information about particles<br>→ to find out <b>why</b> they are existed and created |
| <b>Plan &amp; Design</b> → <b>Fabrication</b> → <b>Measurement</b> |   |
| <b>How</b>   | <b>How</b> particle interacts with materials  |
| <b>Where</b>   | Position <b>where</b> interaction happens   |
| <b>When</b>  | Time <b>when</b> interaction happens  |
| <b>Who/Which</b>   | <b>Which</b> particles → PID  |
| <b>What</b>  | <b>What</b> characteristics of particles  |

We design, fabricate, test, and use the **readout system (or fast electronics)** for data acquisition (DAQ).

# Readout scheme for data acquisition (DAQ)



# Components of waveform

Base line  
Pulse height  
Pulse width

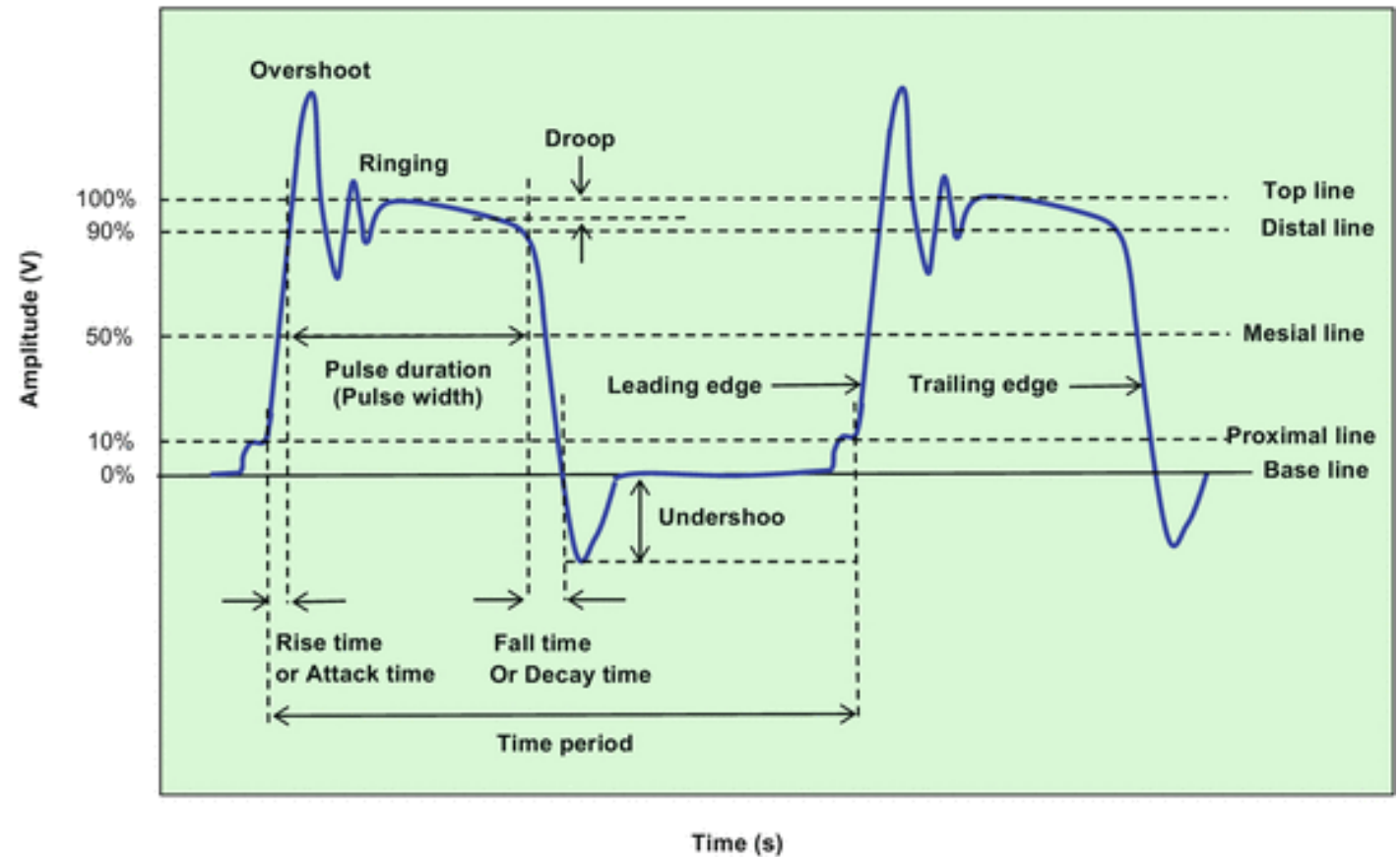
Proximal line: 10% of pulse height  
Mesial line: 50% of pulse height  
Distal line: 90% of pulse height

Rise time (or attack time) at leading edge  
Fall time (or decay time) at trailing edge  
→ These depend on the polarity of waveform.

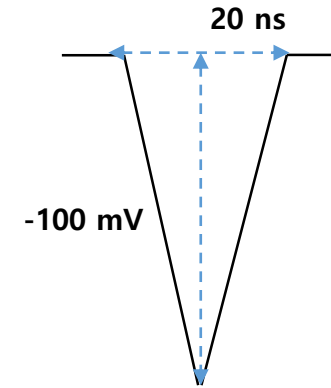
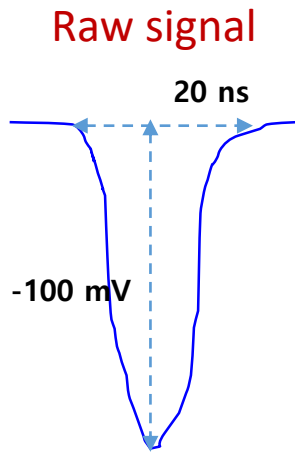
Overshoot  
Undershoot  
Ringing

Time period

[https://link.springer.com/chapter/10.1007/978-3-319-25448-7\\_7](https://link.springer.com/chapter/10.1007/978-3-319-25448-7_7)



# Charge of raw signal



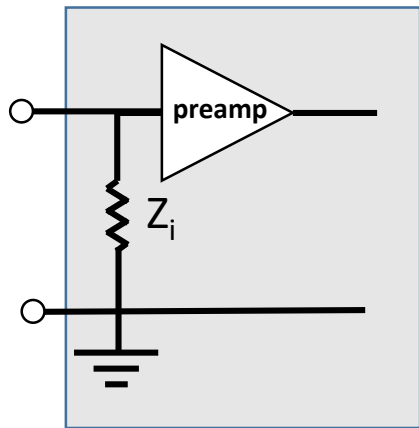
Electric charge of analog signal with assumption:

$$Q(C) = \frac{V(V) \cdot t(s)}{2 \cdot R(\Omega)} = \frac{-0.1 V \cdot 20 ns}{2 \cdot 50 \Omega} = -20 pC$$

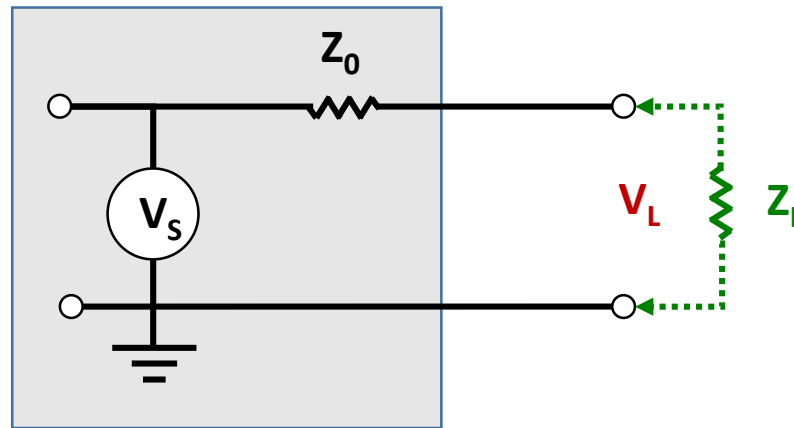
# Device impedances

A basic concept in the processing of pulses from radiation detectors is the impedance of the devices that comprise the signal-processing chain.

Input configuration



output configuration



Voltage ( $V_L$ ) appearing across a loading ( $Z_L$ ) by voltage-divider relation

$$V_L = V_S \frac{Z_L}{Z_0 + Z_L}$$

For the open-circuit or unloaded ( $Z_L = \infty$ ), voltage is  $V_L = V_S$ . → not for the real experiment

To preserve maximum signal level, one normally wants  $V_L$  to be as large a fraction of  $V_S$  as possible. For  $Z_L \gg Z_0$  then  $V_L \cong V_S$  → Fan-In & Fan-Out, Discriminator, ADC, etc

For  $Z_L = Z_0$  then  $V_L = V_S/2$  → Divider or Splitter

# Preamplifier

|                 |  |
|-----------------|--|
| <b>Role</b>     | <b>converting a raw signal from the detector into output signal with gain</b>      |
| <b>Location</b> | <b>placing close to the detector to reduce the noise and avoid the signal loss</b> |

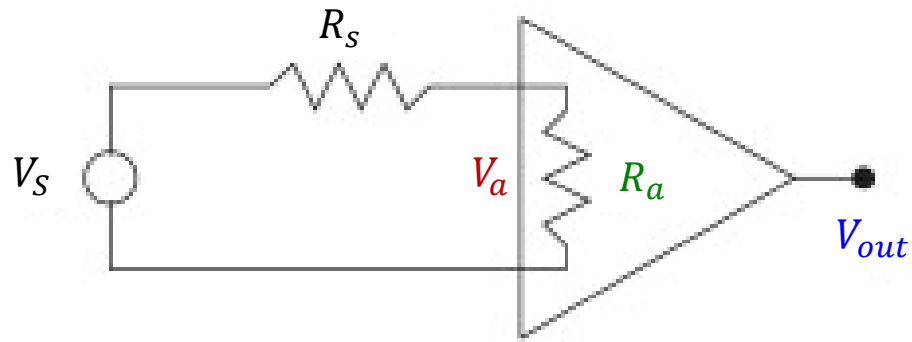
## ✓ **Specification for design**

- Dynamic range
- Size of input signal
- Pulse pileup
- Signal-to-noise ratio
- Power consumption

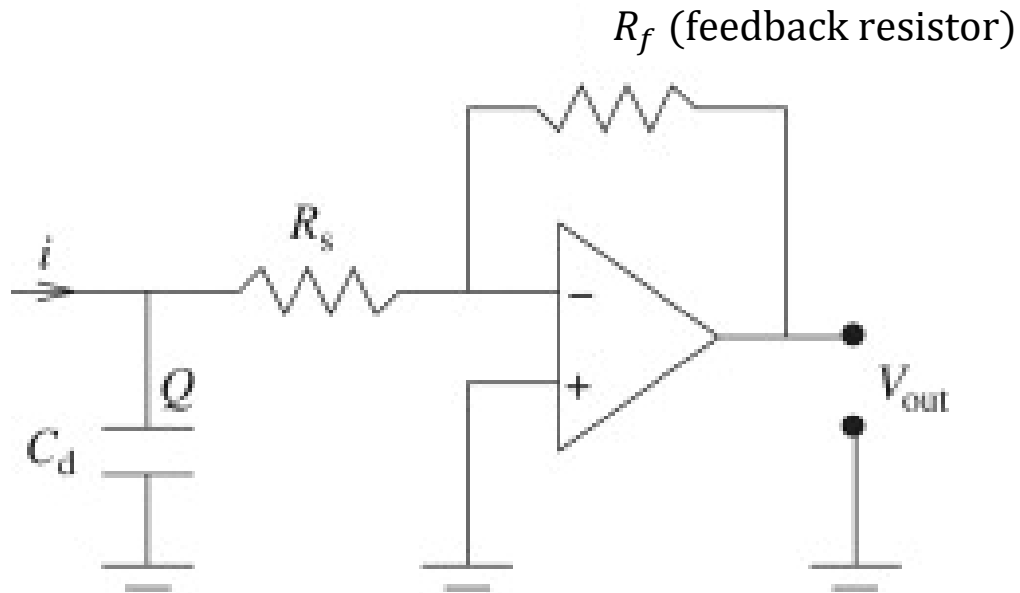
## ✓ **Configuration**

- **Voltage-sensitive preamplifiers**
- Current-sensitive preamplifiers
- **Charge-sensitive preamplifiers**

# Voltage-sensitive preamplifiers



Design principle of V-sensitive preamp



Simplified realistic V-sensitive preamp

Signal voltage  $V_S$   
 Voltage at the input stage of the amplifier  $V_a$   
 Output voltage  $V_{out}$

$$V_a = V_S \frac{R_a}{R_S + R_a}$$

Any current drawn would decrease the potential drop across  $R_S$ .  
 Ideally, its input resistance have to be infinite.  
 But it can only be achieved up to a good approximation.

For  $R_a \gg R_S$  then  $V_a \cong V_S$   
 then  $V_{out} = Gain \times V_a \approx Gain \times V_S$

Signal voltage  $V_S = Q/C_d$

$Q$ : collected charge on the readout electrode ( $Q = \int_0^{t_0} i_s(t) dt$ )

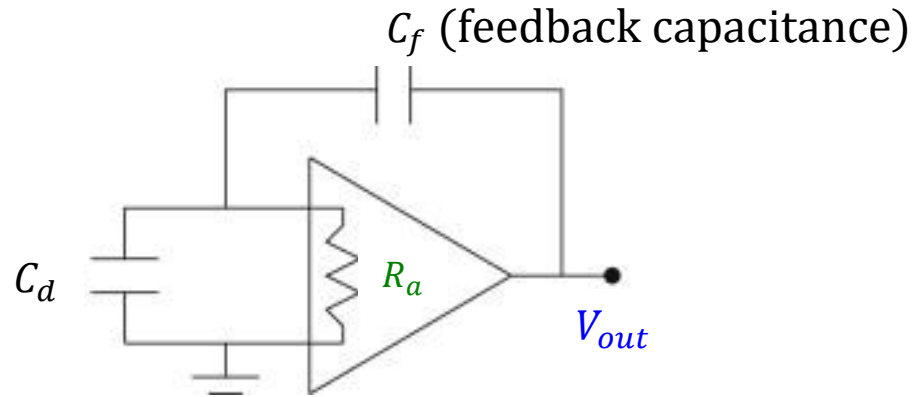
$C_d$ : combined detector and stray capacitance

$$\text{then } V_{out} \approx Gain \times \frac{Q}{C_d} = \frac{Gain}{C_d} \int_0^{t_0} i_s(t) dt$$

Since we are integrating the current to convert it into voltage,  **$C_d$  should discharge slower than the charge collection time  $t_d < R_a C_d$ .**

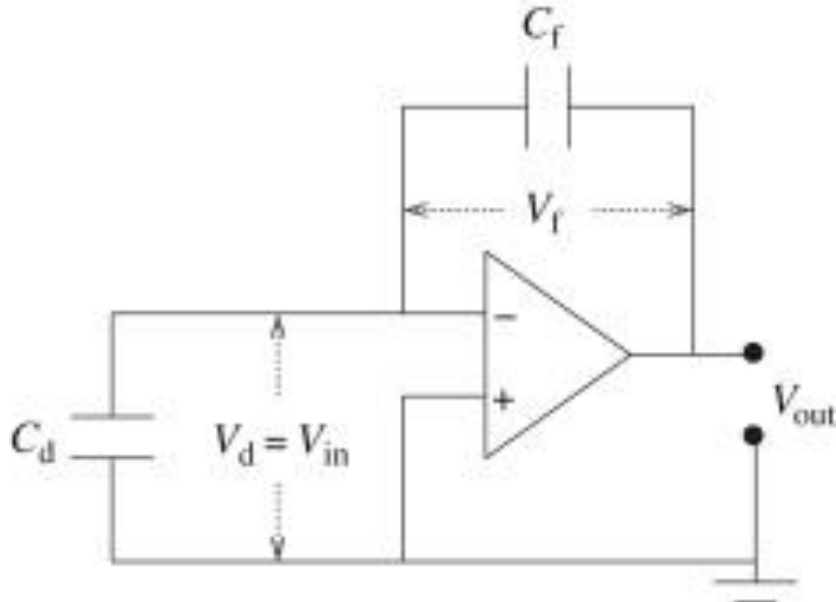


# Charge-sensitive preamplifiers



Basic principle of Q-sensitive preamp

The dependence of a voltage-sensitive preamplifier on the input capacitance is a serious problem for many detection systems.  
 → to develop Q-sensitive preamplifiers

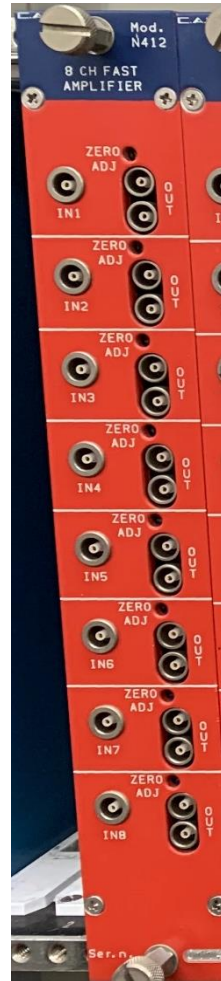


Simple Q-sensitive preamp

The charge ( $Q_d$ ) accumulated on the electrode ( $C_d$ ) is integrated on another capacitor ( $C_f$ ). Then the potential ( $V_f$ ) on that capacitor is then directly proportional to the original charge ( $Q_d$ ) on the detector.

$$V_{out} \propto \frac{Q_f}{C_f} \propto \frac{Q_d}{C_f}$$

The condition that  $Q_f \approx Q_d$  can only be achieved if no current flows into the preamplifier's input with  $R_a \rightarrow \infty$ .



## CAEN N412 8ch Fast Amplifier

### INPUTS:

- 50 $\Omega$  impedance.
- Reflection coefficient:  $\leq 6\%$  over input dynamic range.

- Quiescent voltage:  $< \pm 5$  mV.

### OUTPUTS:

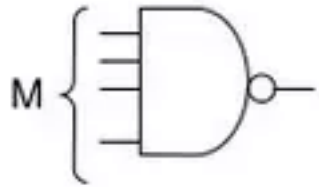
- Risettime:  $\leq 3.0$  ns.
- Falltime:  $\leq 2.0$  ns.
- Maximum positive amplitude (linear): 400 mV (50 $\Omega$  impedance).
- Maximum negative amplitude (linear): -4 V (50 $\Omega$  impedance).
- Overshoot:  $\pm 10\%$  for input risetimes of 2 ns and with the 2nd output terminated in 50 $\Omega$ .
- Quiescent voltage adjustable (via front panel trimmer for each channel) in the range from -20 mV to +50 mV.

### GENERAL:

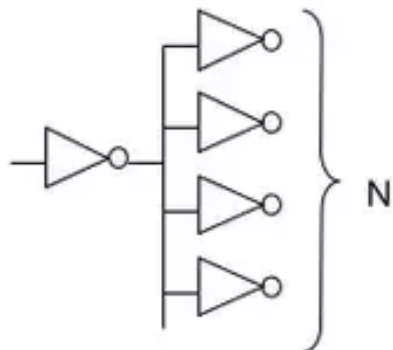
- Gain: fixed  $10 \pm 3\%$ , non-inverting.
- Coupling: direct.
- I/O delay:  $\leq 12$  ns.
- Noise: less than 1 mV, referred to input.
- Interchannel crosstalk: better than -56 dB in the worst test condition, and with both the outputs of the tested channel terminated in 50 $\Omega$ .
- Bandwidth:
  - 160 MHz (with both the channel's outputs terminated in 50 $\Omega$ );
  - 180 MHz (single ended output).

# Fan-In and Fan-Out (FIFO)

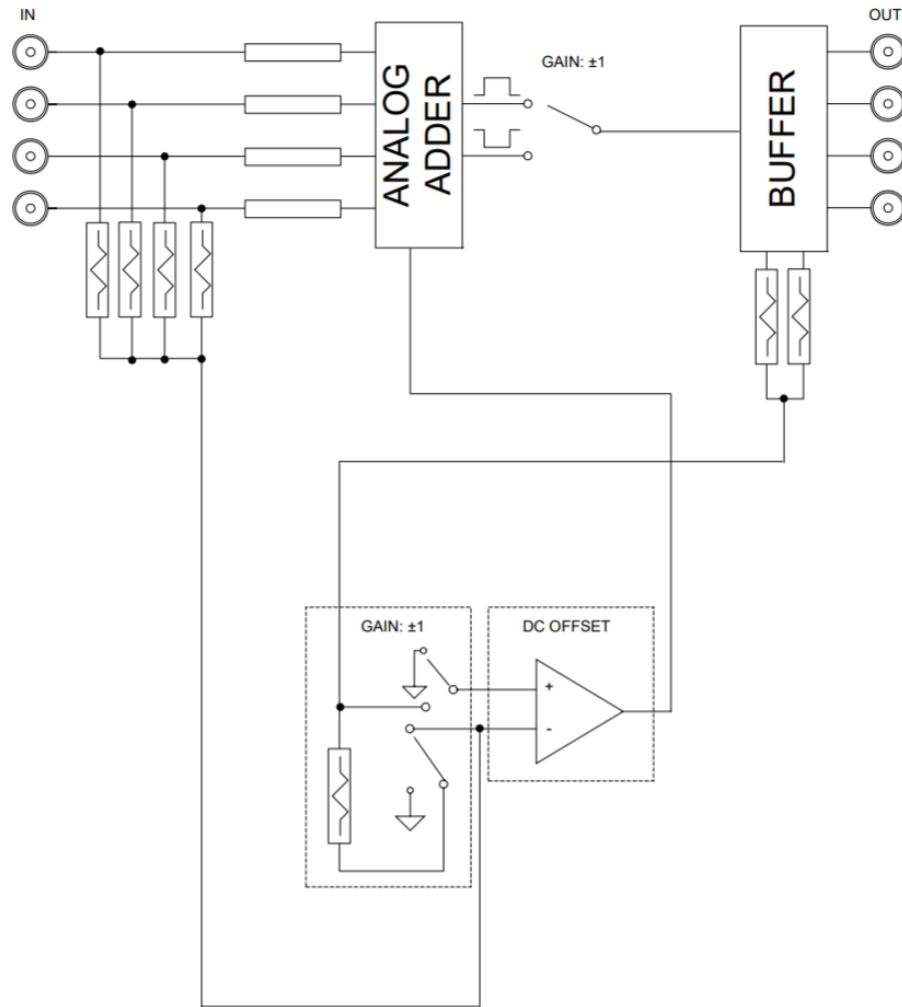
**Fan-in:** maximum number of input signals feeding into the input of a logic system



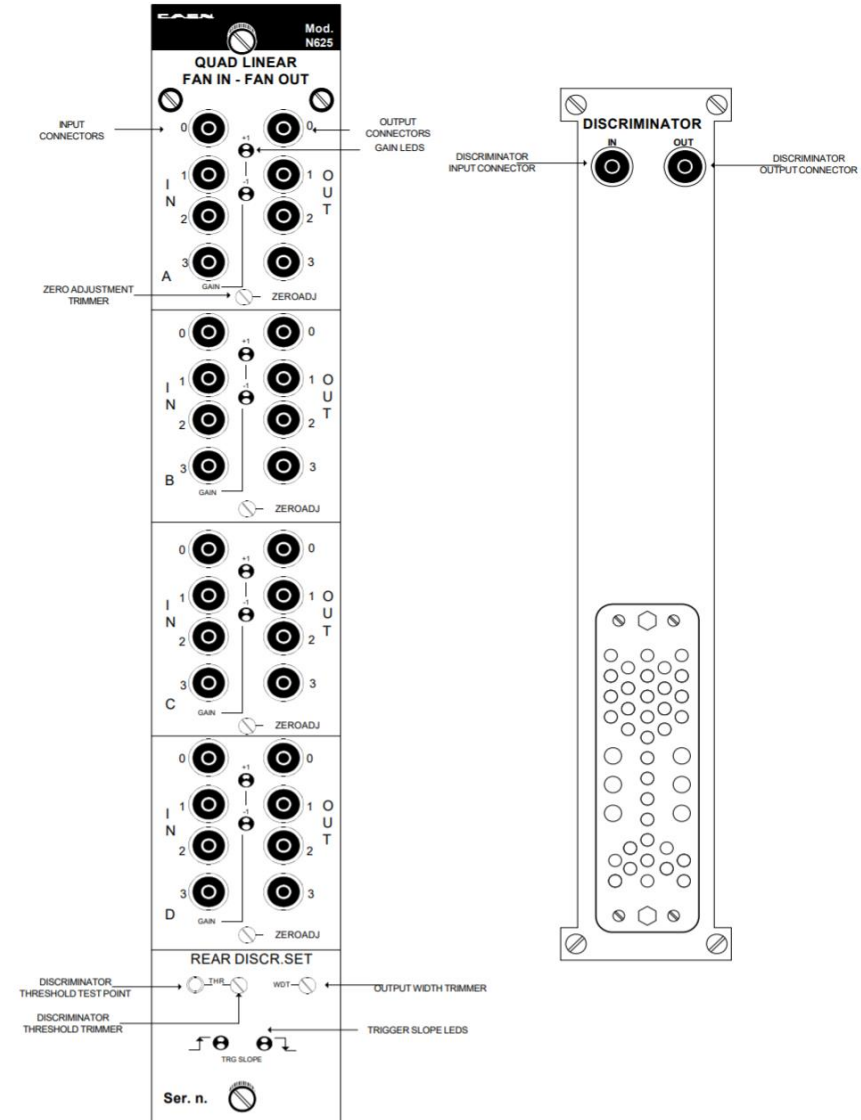
**Fan-out:** maximum number of output signals from the output of a logic system



# Fan-In and Fan-Out (FIFO)



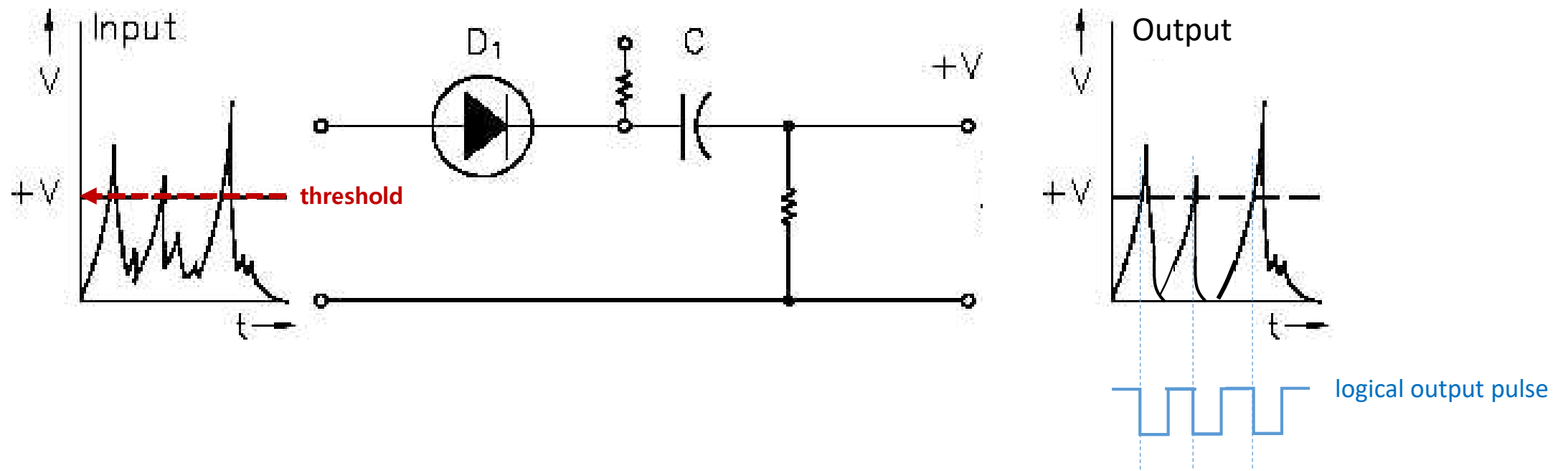
CAEN N625 Quad Linear Fan In / Fan Out



# Discriminator (DISC)

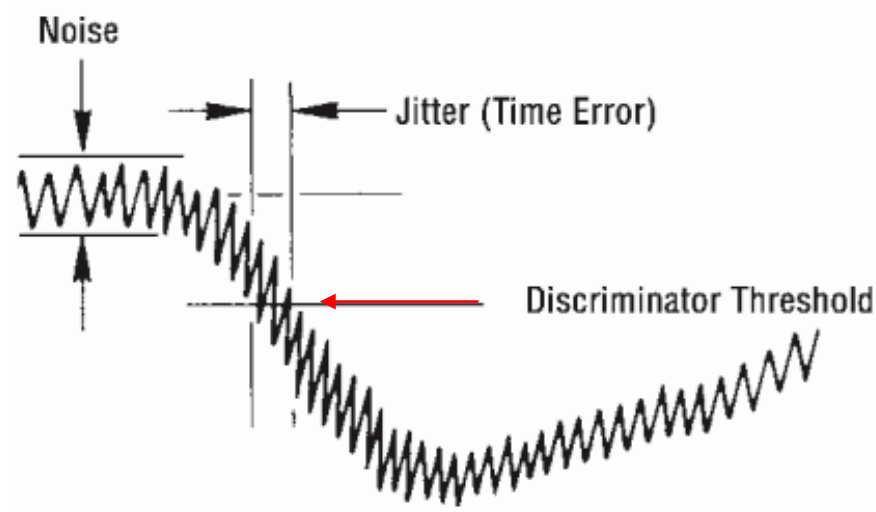
**Role:** generating the logical output pulse when the input pulse exceeds the discriminator preset level

→ If input voltages **exceeds the threshold value +V** then diode  $D_1$  conducts and **DISC generates the logical output pulses.**



# Timing jitter and walk

Timing jitter in a pulse



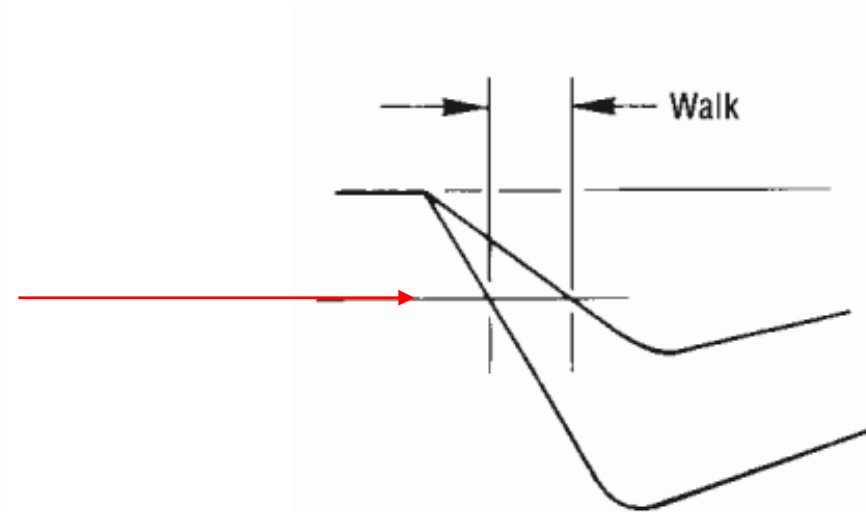
The contribution of noise to the (Timing) Jitter

$$\text{Timing Jitter} = e_{\text{noise}} / (dV/dt)$$

$e_{\text{noise}}$ : voltage amplitude of the noise superimposed on the analog pulse

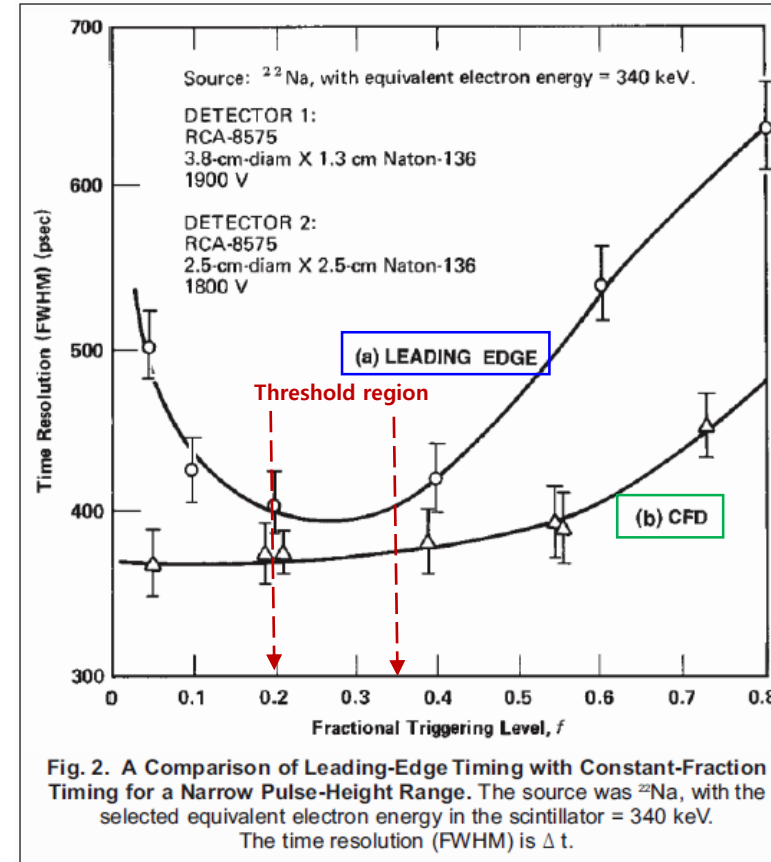
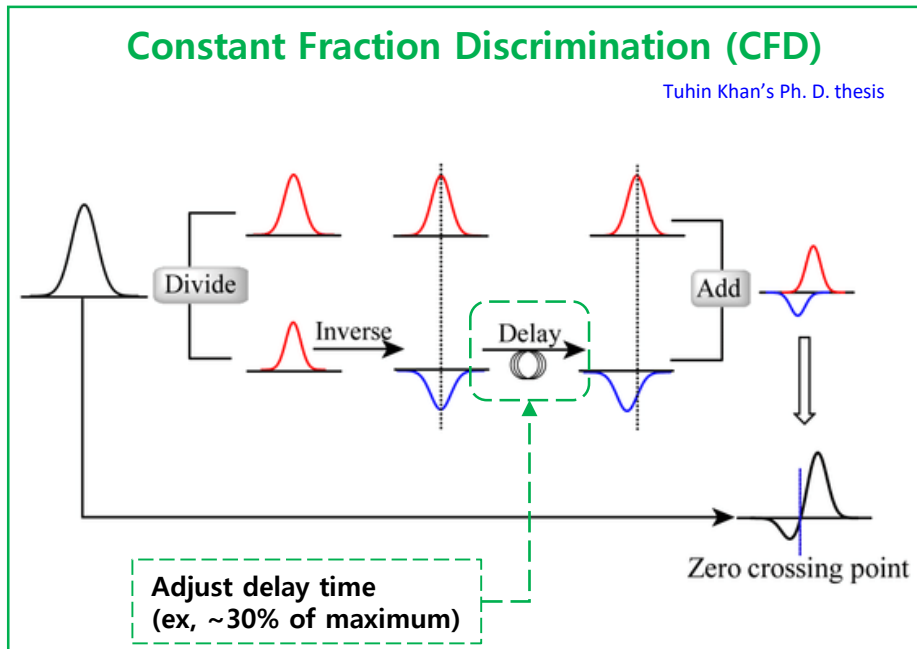
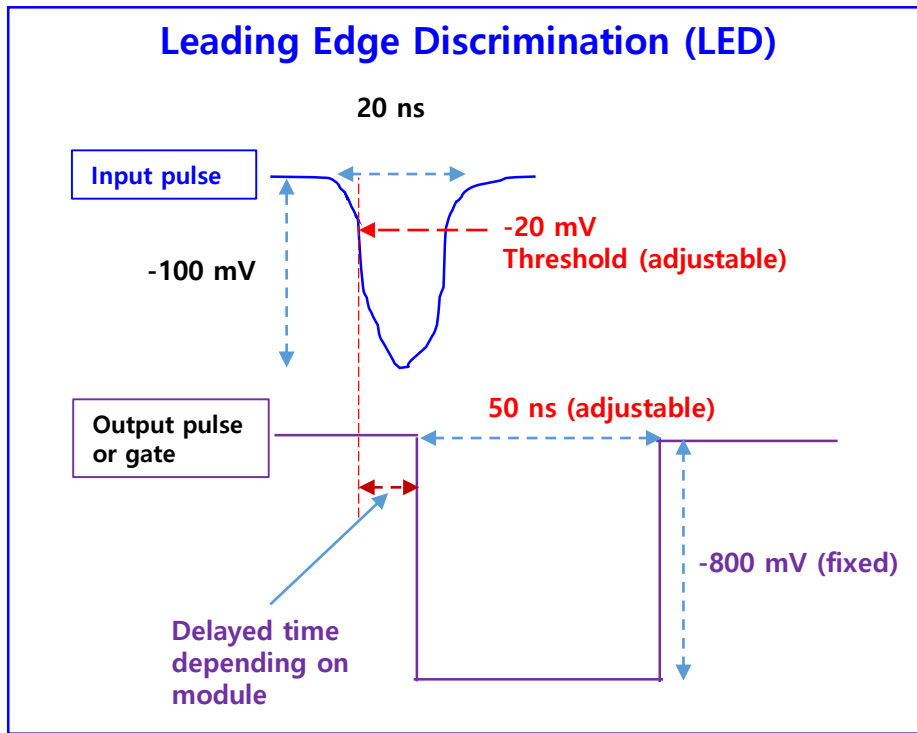
$dV/dt$ : slope of the signal when its leading edge crosses the discriminator threshold

Timing walk among pulses



“(Timing) Walk” is the **systematic dependence** of the time marker on the **amplitude of the input pulse**.

# LED and CFD



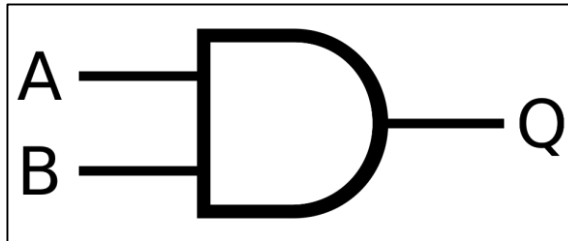
[http://www.peo-radiation-technology.com/wp-content/uploads/2015/09/ort\\_15\\_fast-timing-discriminators\\_datasheet\\_peo.pdf](http://www.peo-radiation-technology.com/wp-content/uploads/2015/09/ort_15_fast-timing-discriminators_datasheet_peo.pdf)

Time resolution:  $\sigma_{\text{CFD}} < \sigma_{\text{LED}}$

# Role of Logic Unit

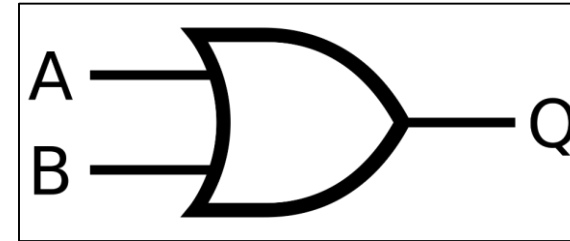
**Role:** generating the gating pulse when the preset of logical algorithm against with inputs is true

**AND logic:**  $A \cdot B$  or  $A \wedge B$



| INPUT |   | OUTPUT |
|-------|---|--------|
| A     | B | Q      |
| 0     | 0 | 0      |
| 0     | 1 | 0      |
| 1     | 0 | 0      |
| 1     | 1 | 1      |

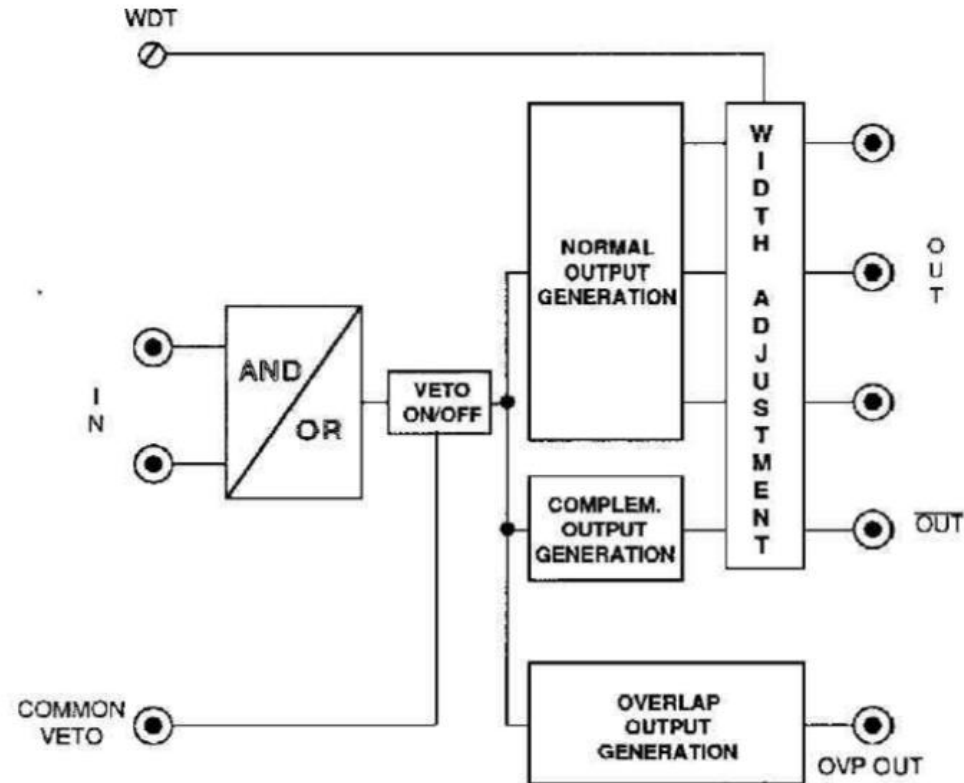
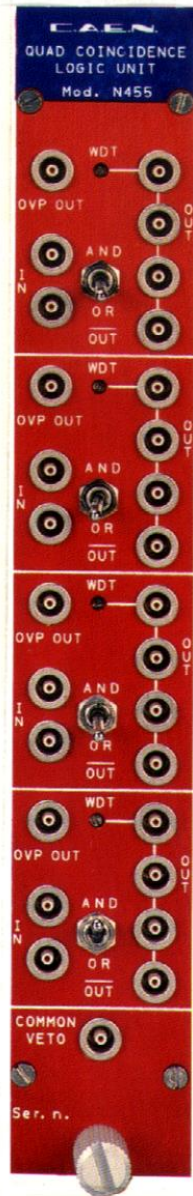
**OR logic:**  $A + B$  or  $A \vee B$



| INPUT |   | OUTPUT |
|-------|---|--------|
| A     | B | Q      |
| 0     | 0 | 0      |
| 0     | 1 | 1      |
| 1     | 0 | 1      |
| 1     | 1 | 1      |



# Logic Unit

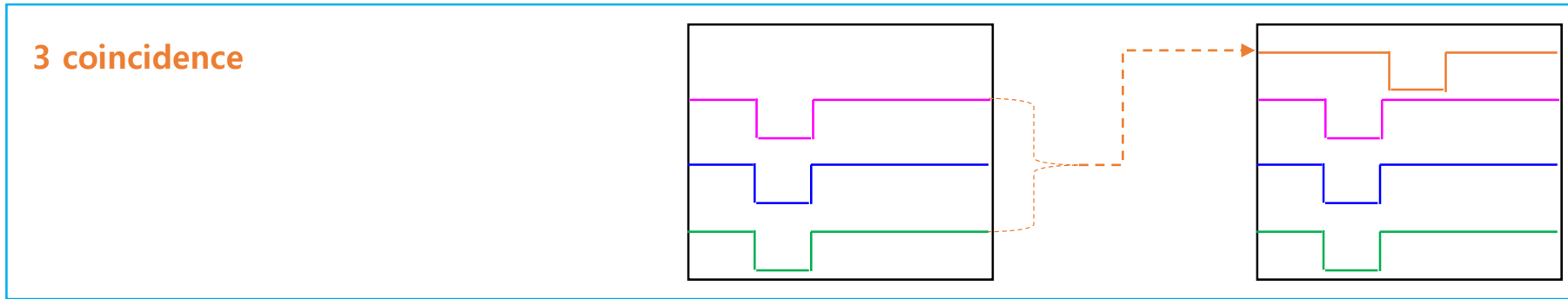


**IMPORTANT NOTE:**  
Unused Outputs require a 50  $\Omega$  termination

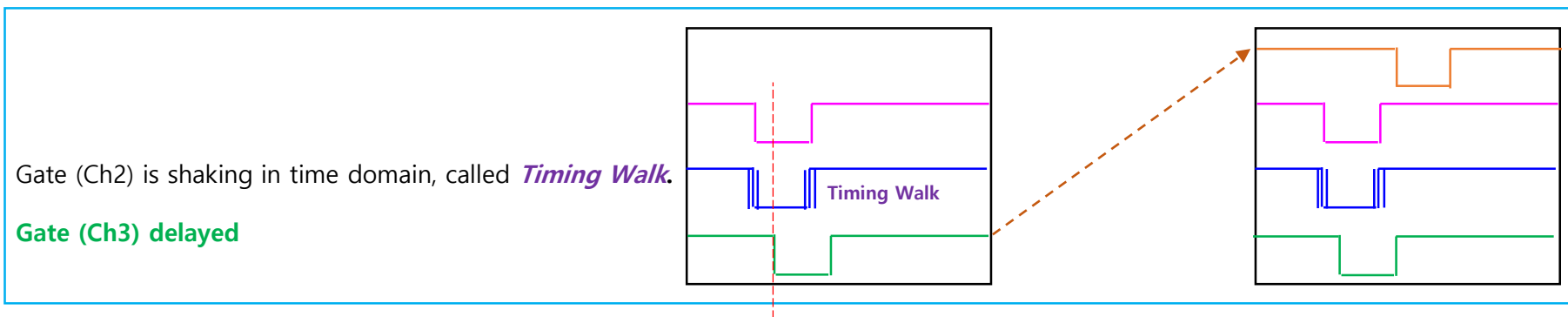
CAEN N455 Quad Coincidence Logic Unit

# Coincidence with 3 inputs

When events occur, the input signals from many detectors can be matched with Logic Unit.

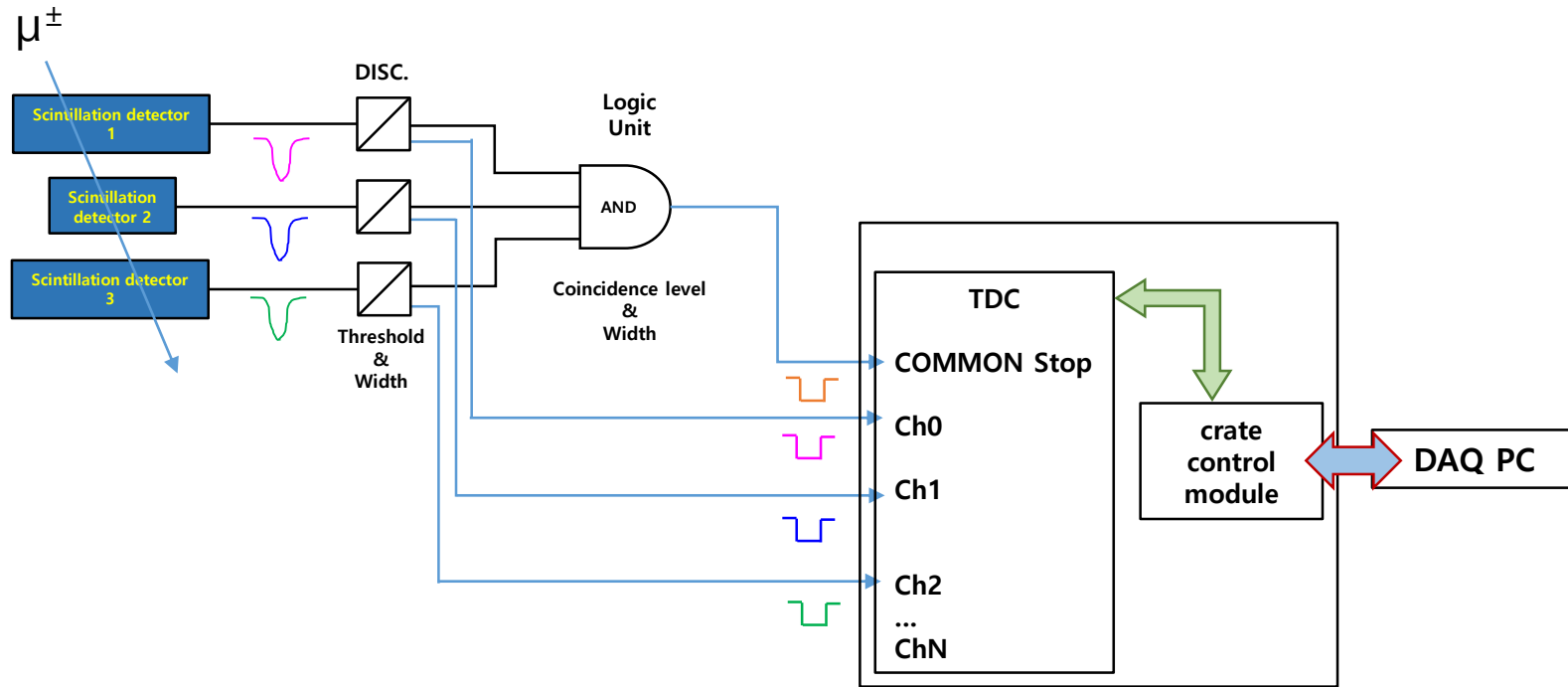


## Coincidence with timing walk

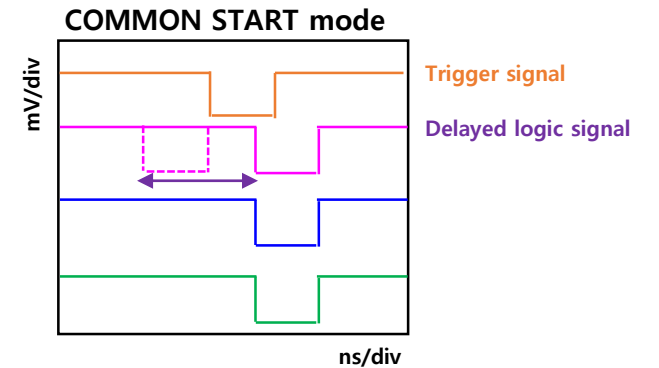
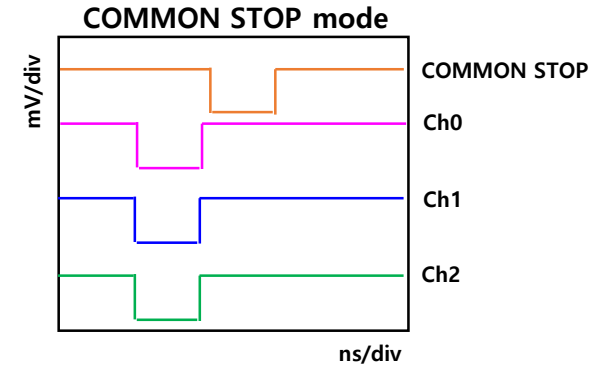


# Time measurements with TDC

Scintillation counter/detector:  
Scintillator + PhotoMultiplier Tube (PMT)

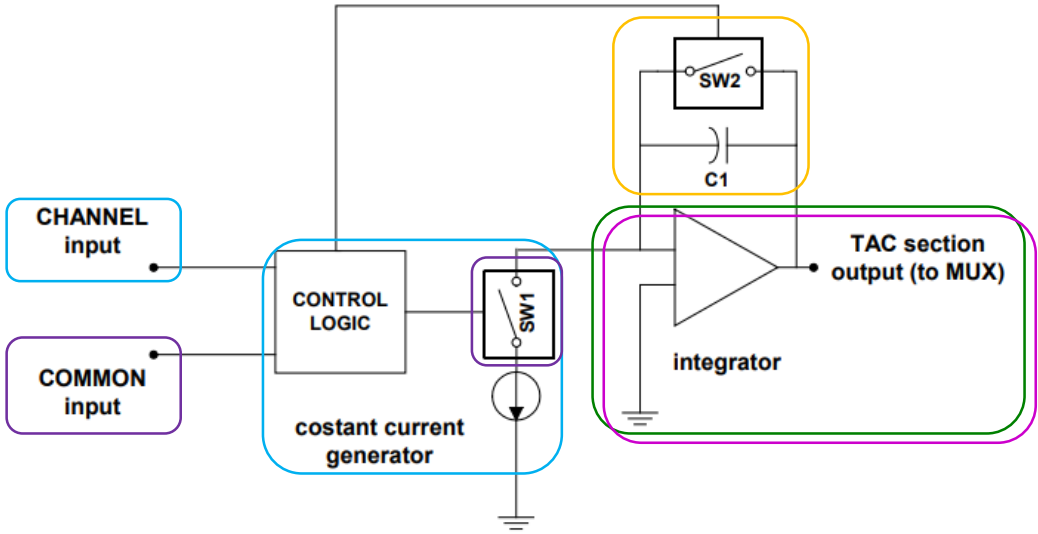


Operation mode of TDC: COMMON STOP/START?



Time-to-Digital Converter (TDC)

# How to record time in TDC?



Block diagram of TAC section in CAEN V775N 16ch MultiEvent TDCs

A Start signal closes the switch SW1 thus allowing a constant current to flow through an integrator; a Stop signal opens the switch SW1 again.



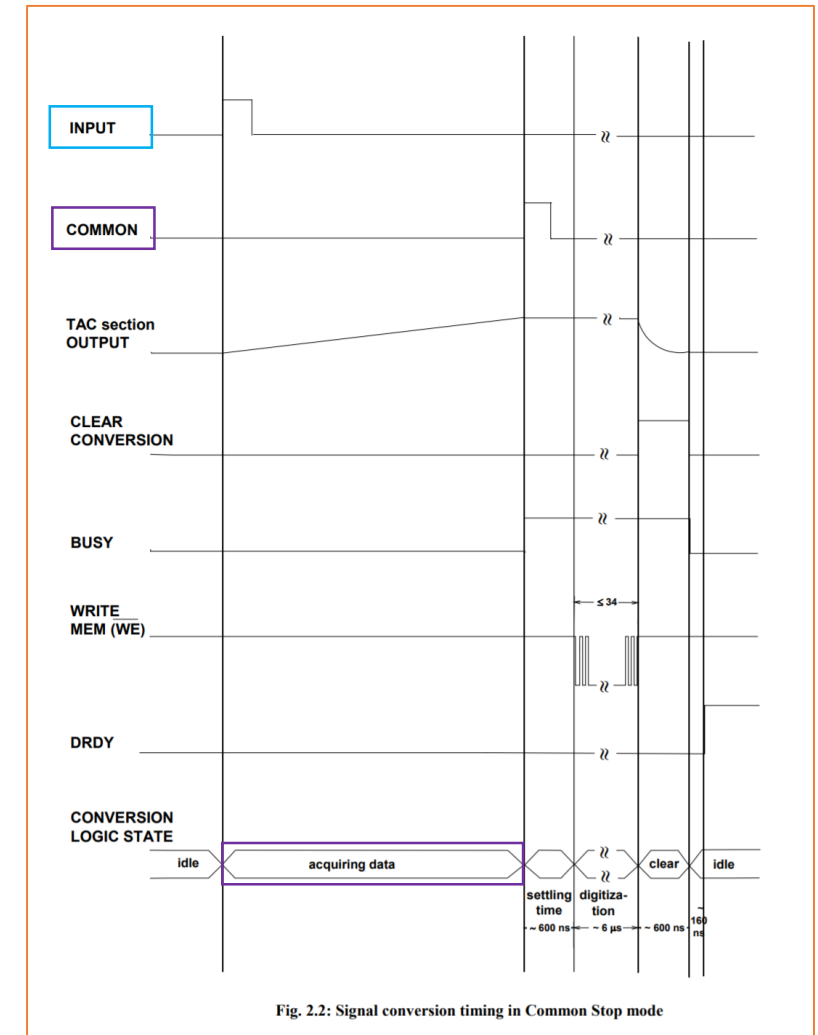
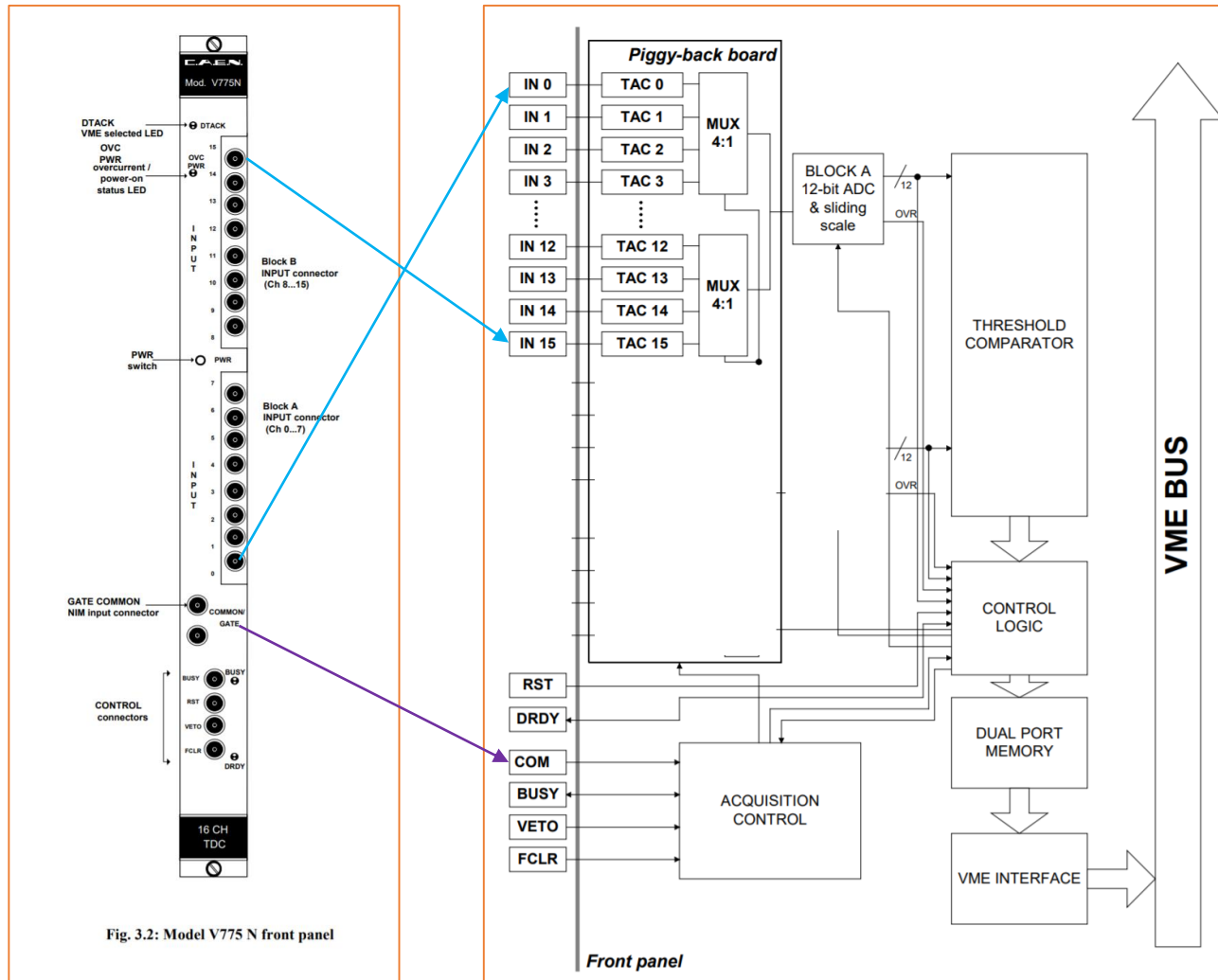
The constant current generates a linear ramp voltage which is stopped at an amplitude proportional to the time interval between Start and Stop pulses. → accumulation on C1



After digitization the SW2 switch is closed by the CLEAR signal which allows the discharge of the capacitor C1.

Both the COMMON and CLEAR signals are controlled by the CONTROL LOGIC section.

# TDC and signal conversion timing



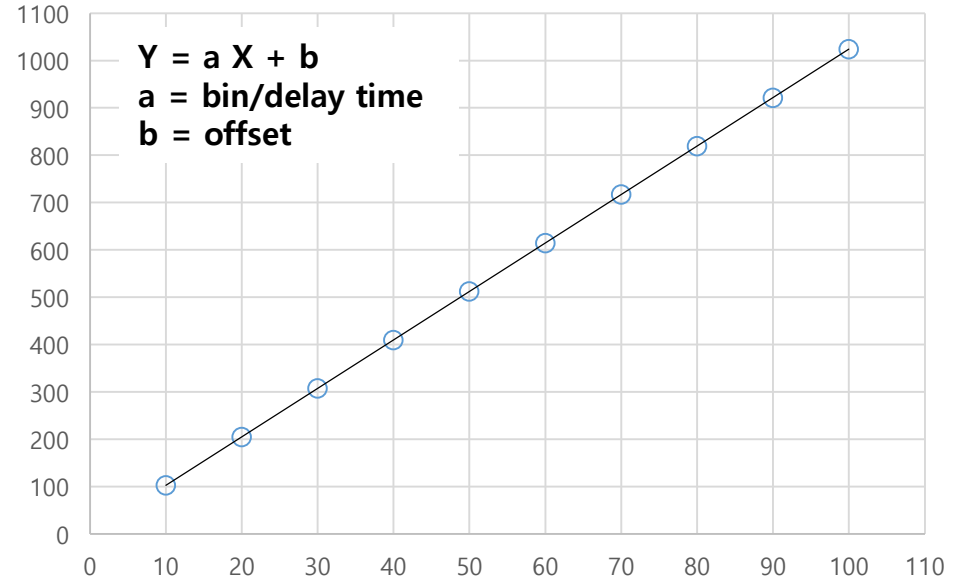
# TDC calibration

T<sub>full</sub> = 100 ns with 10 bit (1024) data set

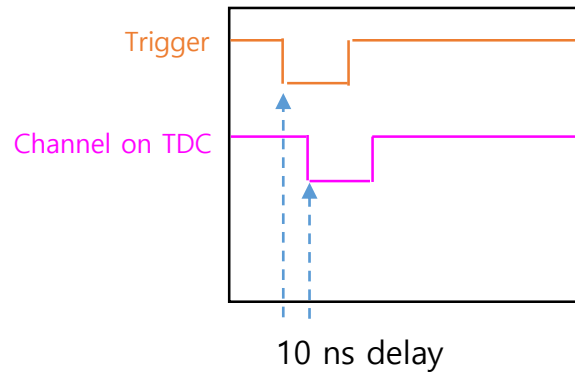
|            |        |
|------------|--------|
| 100        | ns     |
| 1024       | bin    |
| 0.09765625 | ns/bin |

| delay (ns) | unit time (ns/bin) | TDC (bin) |
|------------|--------------------|-----------|
| 10         | 0.09765625         | 102.4     |
| 20         | 0.09765625         | 204.8     |
| 30         | 0.09765625         | 307.2     |
| 40         | 0.09765625         | 409.6     |
| 50         | 0.09765625         | 512       |
| 60         | 0.09765625         | 614.4     |
| 70         | 0.09765625         | 716.8     |
| 80         | 0.09765625         | 819.2     |
| 90         | 0.09765625         | 921.6     |
| 100        | 0.09765625         | 1024      |

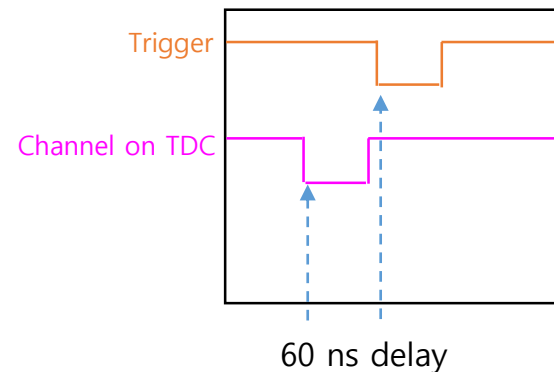
TDC (bin) vs Delay time (ns)



COMMON START MODE

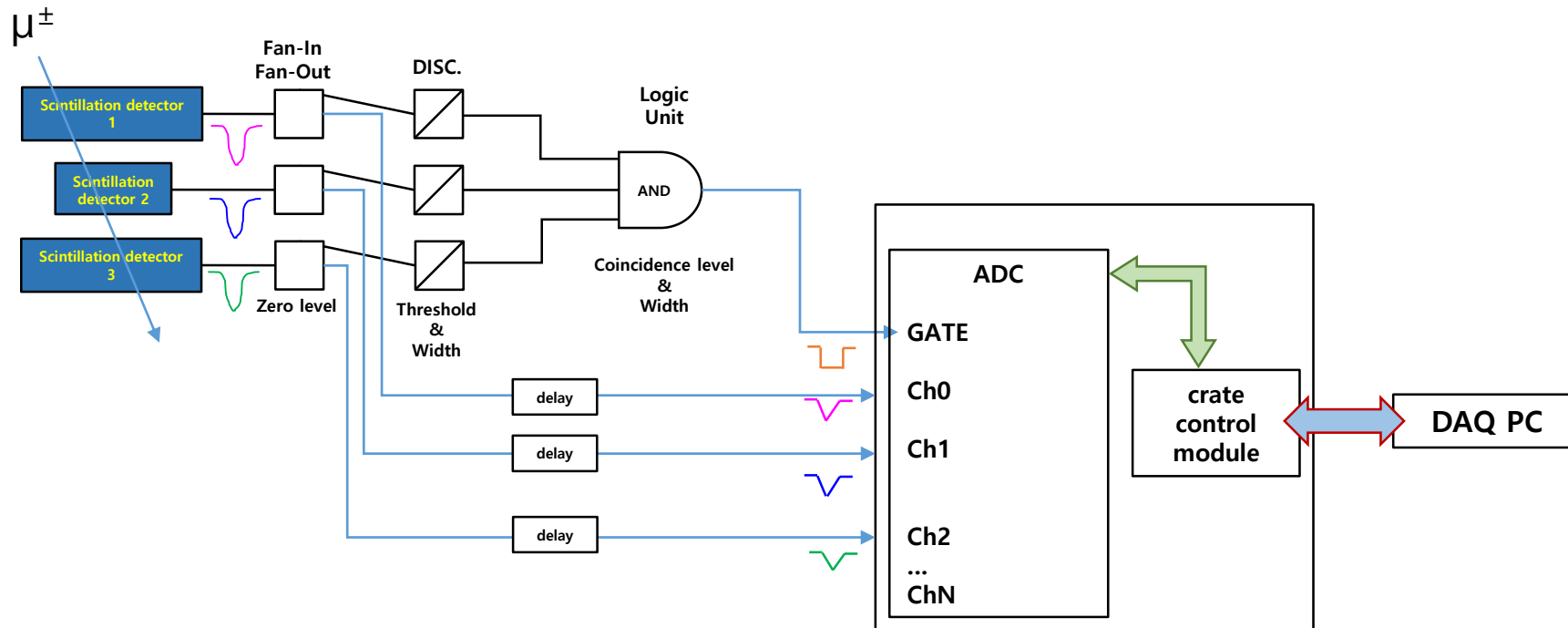


COMMON STOP MODE

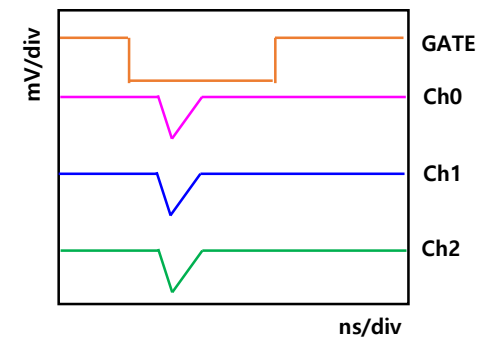


# Charge measurements with ADC

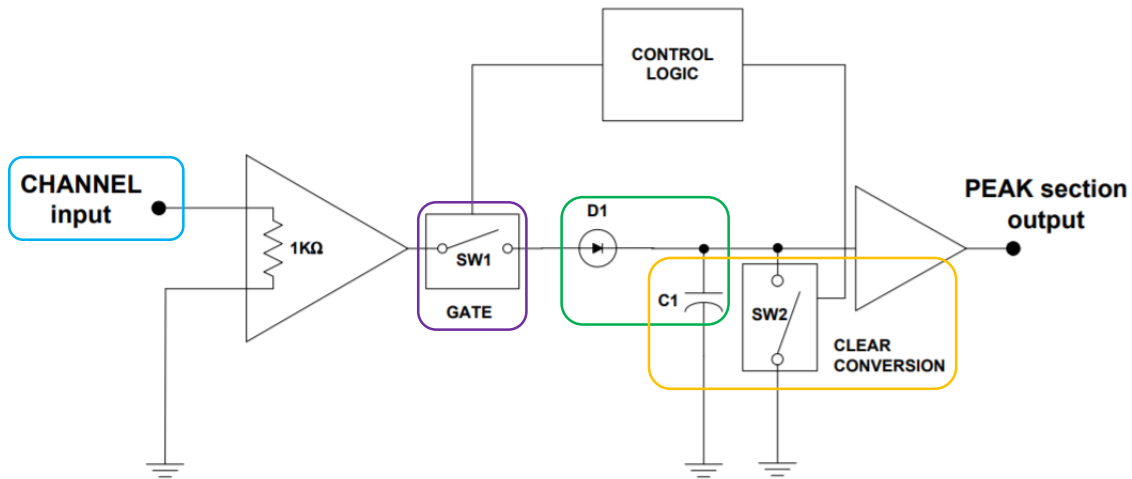
Scintillation counter/detector:  
Scintillator + PhotoMultiplier Tube (PMT)



Time domain of signals for ADC



# How to record charge in ADC?



## COMMON STOP mode

The **GATE signal** closes the **switch SW1** thus allowing the **capacitor C1** to be charged as the **diode D1** is forward-biased by the signal.



As the **SW1** is open again, the signal is digitized by the 12-bit ADCs.



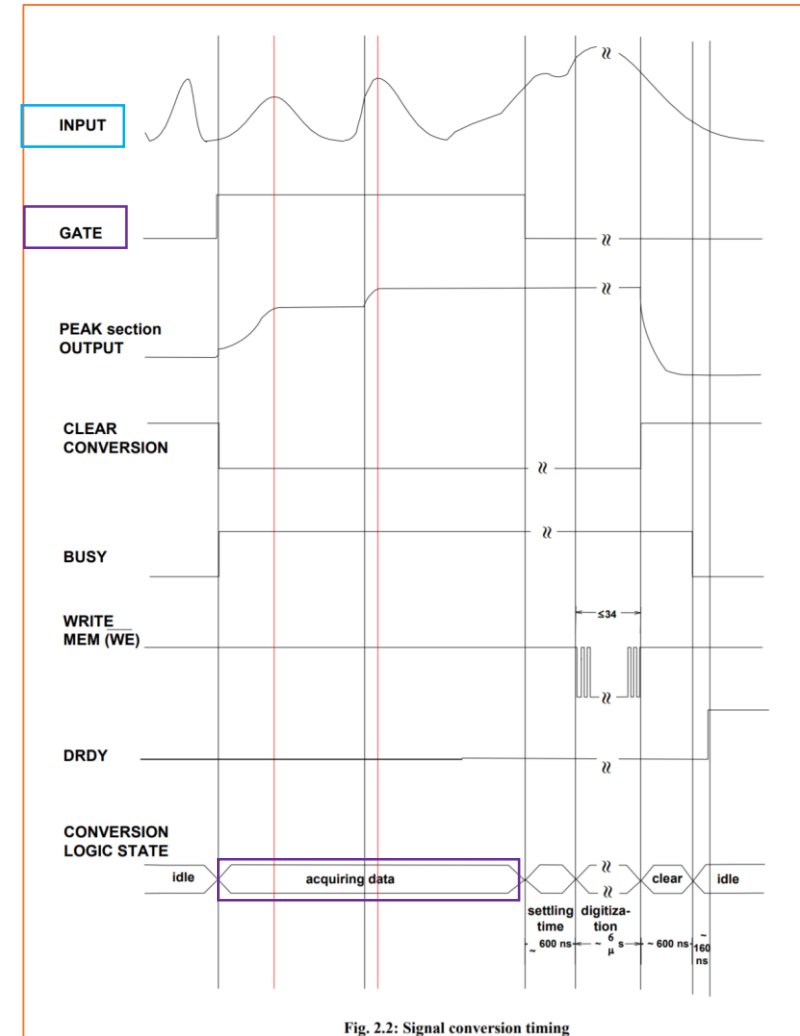
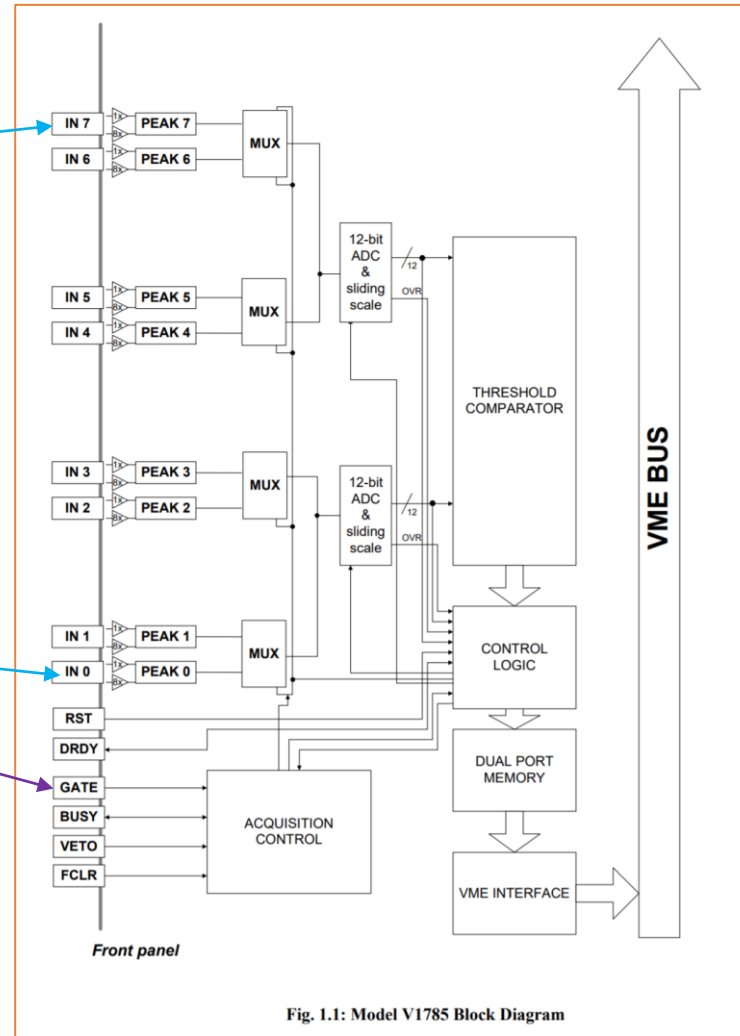
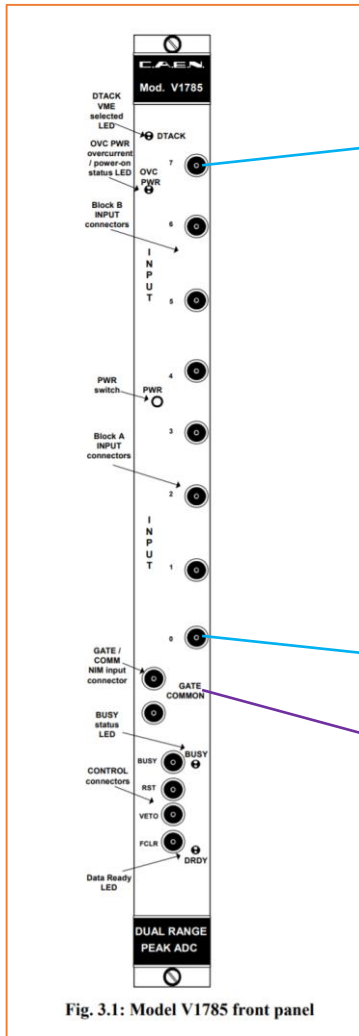
After digitization the **SW2 switch** is closed by the CLEAR signal which allows the discharge of the **capacitor C1**.

Both the GATE and CLEAR signals are controlled by the CONTROL LOGIC section.

Block diagram of PEAK section in CAEN V1785 8ch Dual Range Peak ADC



# ADC and signal conversion timing



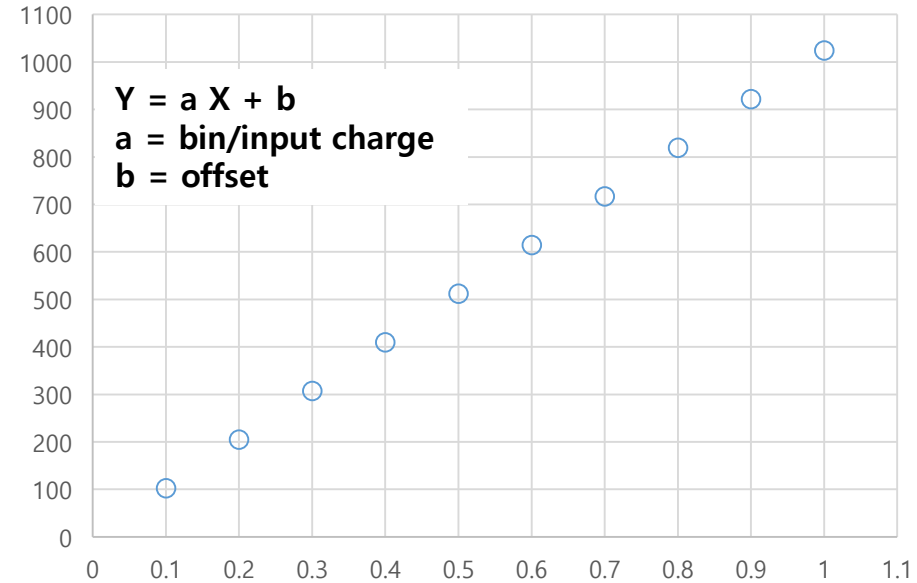
# ADC calibration

Q<sub>full</sub> = 1 pC with 10 bit (1024) data set

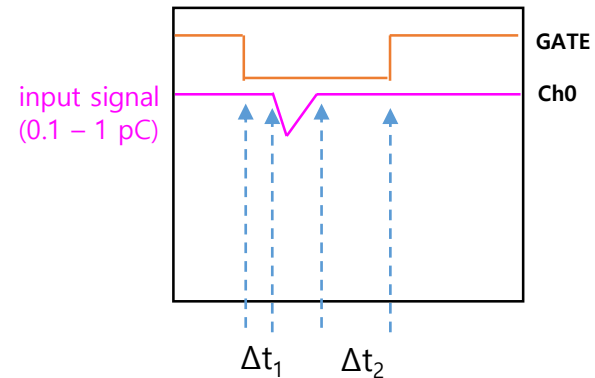
|                   |
|-------------------|
| 1 pC              |
| 1024 bin          |
| 0.00097656 pC/bin |

| Q <sub>in</sub> (pC) | unit time (pC/bin) | ADC (bin) |
|----------------------|--------------------|-----------|
| 0.1                  | 0.000976563        | 102.4     |
| 0.2                  | 0.000976563        | 204.8     |
| 0.3                  | 0.000976563        | 307.2     |
| 0.4                  | 0.000976563        | 409.6     |
| 0.5                  | 0.000976563        | 512       |
| 0.6                  | 0.000976563        | 614.4     |
| 0.7                  | 0.000976563        | 716.8     |
| 0.8                  | 0.000976563        | 819.2     |
| 0.9                  | 0.000976563        | 921.6     |
| 1                    | 0.000976563        | 1024      |

ADC (bin) vs input charge (pC)



Time domain of signals for ADC calibration



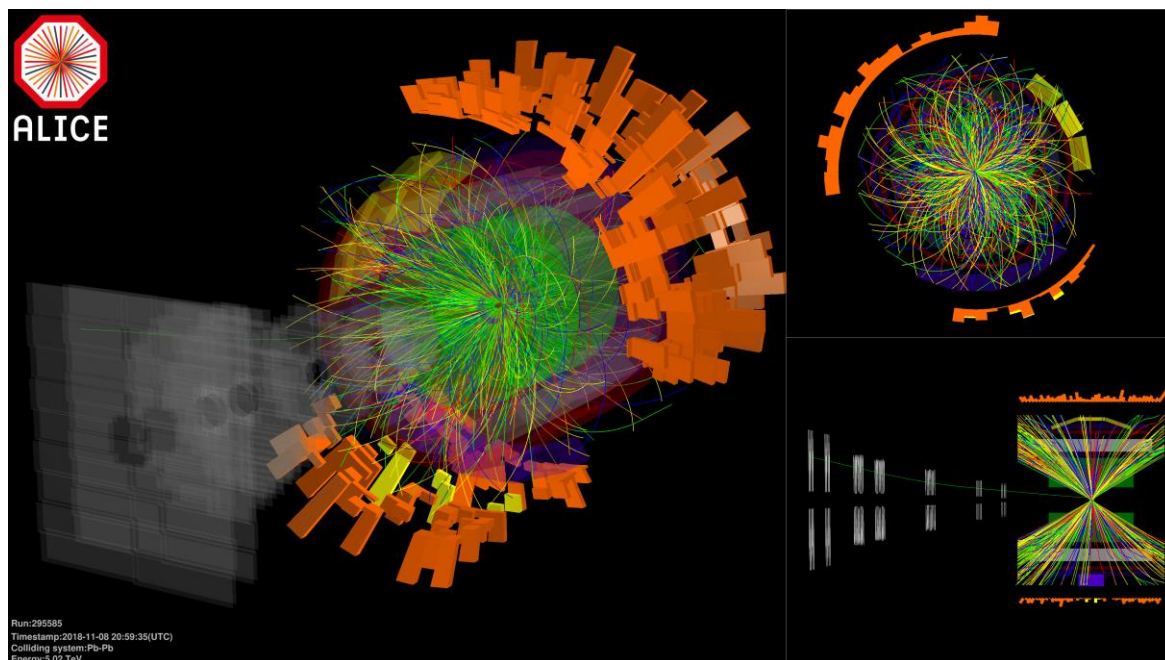
$\Delta t_1$  and  $\Delta t_2$  depends on charge and shape of signal (ex, 10 ns or more).

# Summary: Event in HEP experiment

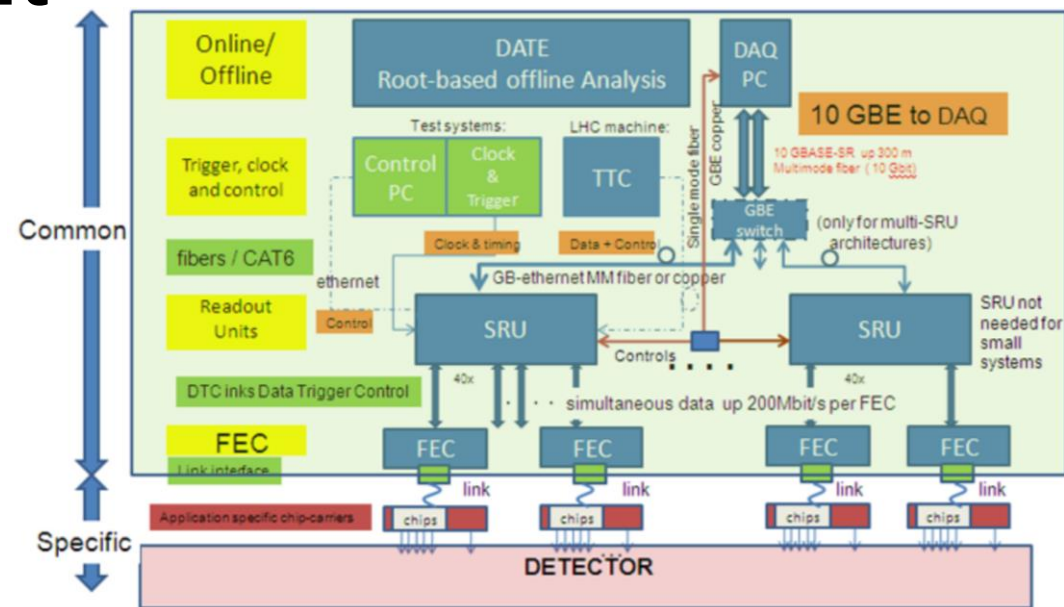
“Fast Electronics” are a main component of particle detection system to see what happens in the HEP experiments.

First Pb collision of ALICE experiment at  $\sqrt{s} = 5.02$  TeV in 2018

<https://cds.cern.ch/record/2646381>

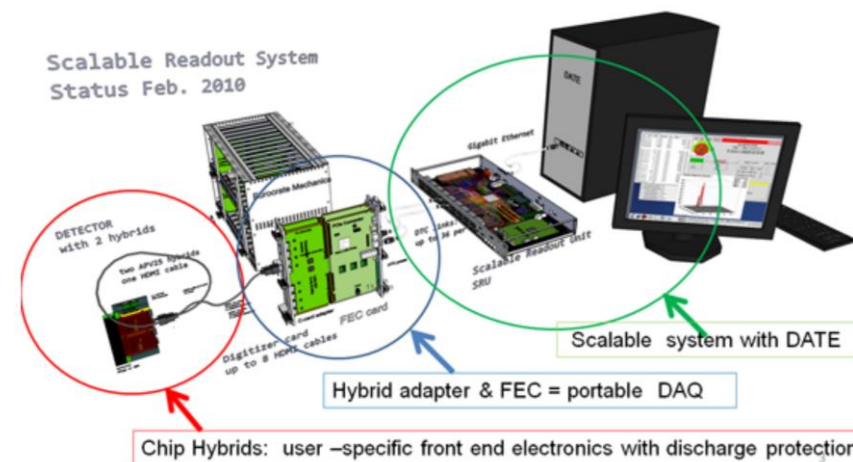


## RD51 Scalable Readout System (SRS)



<https://indico.cern.ch/event/77597/contributions/2088463/attachments/1056845/1506857/RD51-SRS-Description.pdf>

## physical overview SRS of RD51




# Thank you


# Radio Guide (RG) Cables

<http://www.l-com.com/content/Article.aspx?Type=N&ID=10336>


Signal transmission

| RG174/U   |  | NOMINAL ATTENUATION |           |         |
|---|--|---------------------|-----------|---------|
|  |  | MHz                 | db/100 ft | db/100m |
| 50 Ohm Impedance  |  | 50                  | 5.8       | 19.0    |
|   |  | 100                 | 8.4       | 27.6    |
|   |  | 200                 | 12.5      | 41.0    |
|   |  | 400                 | 19.0      | 62.3    |
|   |  | 1000                | 34.0      | 111.5   |


  

| RG316/U   |  | NOMINAL ATTENUATION |           |         |
|---|--|---------------------|-----------|---------|
|  |  | MHz                 | db/100 ft | db/100m |
| 50 Ohm Impedance  |  | 50                  | 5.6       | 18.4    |
|   |  | 100                 | 8.3       | 27.2    |
|   |  | 200                 | 12.0      | 39.4    |
|   |  | 400                 | 17.5      | 57.4    |
|   |  | 1000                | 29.0      | 95.1    |


  

| RG58C/U   |  | NOMINAL ATTENUATION |           |         |
|---|--|---------------------|-----------|---------|
|  |  | MHz                 | db/100 ft | db/100m |
| 50 Ohm Impedance  |  | 50                  | 3.3       | 10.8    |
|   |  | 100                 | 4.9       | 16.1    |
|   |  | 200                 | 7.3       | 23.9    |
|   |  | 400                 | 11.0      | 36.1    |
|   |  | 1000                | 20.0      | 65.6    |


HV transmission

| RG59A/U   |  | NOMINAL ATTENUATION |           |         |
|---|--|---------------------|-----------|---------|
|  |  | MHz                 | db/100 ft | db/100m |
| 75 Ohm Impedance  |  | 50                  | 2.8       | 9.2     |
|   |  | 100                 | 4.0       | 13.1    |
|   |  | 200                 | 5.9       | 19.4    |
|   |  | 400                 | 8.5       | 27.9    |
|   |  | 1000                | 13.8      | 45.3    |

| RG59B/U   |  | NOMINAL ATTENUATION |           |         |
|---|--|---------------------|-----------|---------|
|  |  | MHz                 | db/100 ft | db/100m |
| 75 Ohm Impedance  |  | 50                  | 2.4       | 7.9     |
|   |  | 100                 | 3.4       | 11.1    |
|   |  | 200                 | 4.9       | 16.1    |
|   |  | 400                 | 7.0       | 23.0    |
|   |  | 1000                | 12.0      | 39.3    |

| RG6/U   |  | NOMINAL ATTENUATION |           |         |
|---|--|---------------------|-----------|---------|
|  |  | MHz                 | db/100 ft | db/100m |
| 75 Ohm Impedance  |  | 50                  | 1.5       | 4.9     |
|   |  | 100                 | 2.1       | 6.9     |
|   |  | 200                 | 3.1       | 10.2    |
|   |  | 400                 | 4.5       | 14.8    |
|   |  | 1000                | 7.3       | 23.9    |

How fast signals move in cables?  $v_{\text{signal}} = \sim 5 \text{ ns/m}$

|              | c (m/s)  | Velocity Fraction (%) | v (m/s)  | v (m/ns) | v (cm/ns)   | Connector type |
|--------------|----------|-----------------------|----------|----------|-------------|----------------|
| Vacuum       | 3.00E+08 | 1                     | 3.00E+08 | 0.300    | 30.0        |                |
| <b>RG174</b> | 3.00E+08 | 0.66                  | 1.98E+08 | 0.198    | <b>19.8</b> | <b>LEMO</b>    |
| <b>RG316</b> | 3.00E+08 | 0.79                  | 2.37E+08 | 0.237    | 23.7        | <b>LEMO</b>    |
| <b>RG58</b>  | 3.00E+08 | 0.66                  | 1.98E+08 | 0.198    | 19.8        | <b>BNC</b>     |

Power loss  $\alpha_p \text{ (dB/km)} = \frac{10}{L} \log_{10} \left( \frac{P_1}{P_2} \right)$

$\alpha_p$  = power attenuation, or loss between source and destination, unit (dB/km)  
 $P_1$  = power at the beginning (Source), unit (W)  
 $P_2$  = power at the end (Destination), unit (W)  
 $L$  = distance between  $P_1$  and  $P_2$ , unit (km)

If  $P_1 = 1 \text{ W}$ ,  $P_2 = 0.5 \text{ W}$ , and  $L = 0.1 \text{ km}$ ,  $\alpha_p = \frac{10}{0.1} \log_{10}^{(1/0.5)} = 3.01 \text{ dB/100m}$

**Power at the distance (L) :**  $P_2 = P_1 \cdot \exp(-\alpha_p L)$

RG58/U: 20 AWG ( $\Phi 0.812 \text{ mm}$ ) bare copper (28.5 pF/ft)  
 RG58A/U: 20 AWG standard thin copper (30.8 pF/ft)  
 RG58C/U: same as RG58A/U but not same outer jacket material

RG59A/U: 22 AWG ( $\Phi 0.644 \text{ mm}$ ) bare compacted copper  
 RG59B/U: 22 AWG solid bare copper covered steel

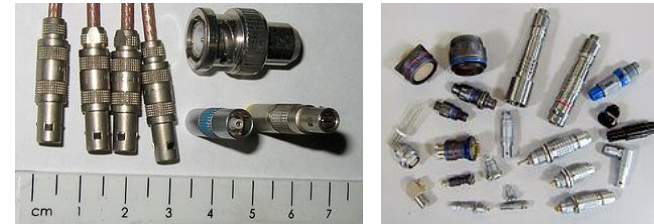
U: Universal  
 AWG: American Wire Gauge



# Connectors for signal and high voltage

## Signal connection

**LEMO** (company founder, engineer **Léon Mouttet**)  
name of an electronic and fibre optic connector manufacturer  
push-pull connectors  
NIM, CAMAC, VME, detector, and etc



**BNC (Bayonet Neill-concelman) connector:** miniature quick connect/disconnect  
50 or 75 ohm impedance  
frequencies below 4 GHz  
voltage below 500 V  
NIM, audio, video, detector and etc



**SMA (Sub Miniature version A):** semi-precision coaxial RF connectors  
screw-type coupling mechanism  
male  $\Phi 0.312$  in ( $\Phi 7.9$  mm)  
0-18 GHz passband (some up to 26.5 GHz)  
detector and etc



## High voltage connection

**MHV (miniature high voltage):** type of RF connector used for terminating a coaxial cable



**SHV (safe high voltage) connector:** safer handling HV than other connectors  
standard: up to 5 kV (5 A)  
higher-version: 20 kV or more  
NIM, detector, and etc



# CAMAC

**Computer Aided Measurement And Control (CAMAC):** a joint specification of the U.S. NIM and the European ESONE committees for a modular, high-performance, real-time data acquisition and control system concept.

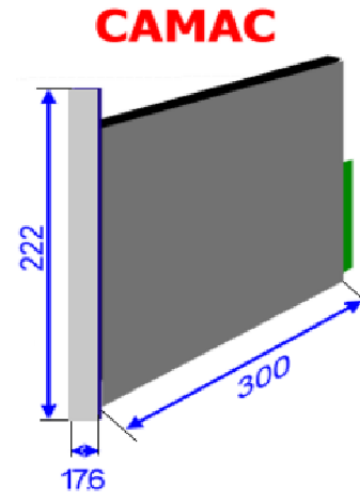
CAMAC was introduced in 1969 by ESONE and fully defined in 1971 with the standards EUR4100 and EUR4600 / IEEE Standard 583-1982 (reaffirmed 1994) "Modular Instrumentation and Digital Interface System (CAMAC)".

It represents a complementation of the NIM standard for computer based experiment control and data acquisition. Main field of CAMAC use are computer based control and data acquisition systems in nuclear and high-energy physics experiments but in the past also in industrial applications, aerospace, and defense test systems.

All CAMAC bus signals are TTL logic levels as given in the following table:

|                           | <b>Logic 0</b> | <b>Logic 1</b> |
|---------------------------|----------------|----------------|
| <b>Input must accept</b>  | +2.0 to 5.5V   | 0 to +0.8V     |
| <b>Output must accept</b> | +3.5 to 5.5V   | 0 to +0.5V     |

**Size: H222xW17.6xD300 mm (except backplane power connector)**



**CAMAC Pin assignment (viewed from front)**

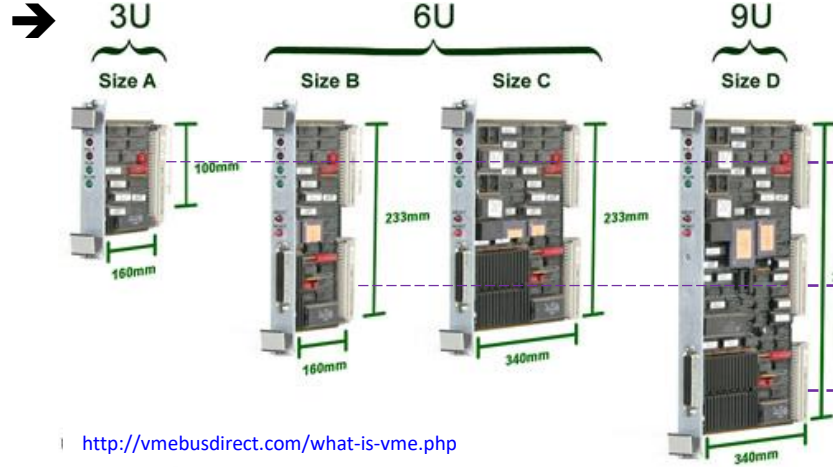
| Controller station |     | Normal station |     |
|--------------------|-----|----------------|-----|
| P1                 | B   | P1             | B   |
| P2                 | F16 | P2             | F16 |
| P3                 | F8  | P3             | F8  |
| P4                 | F4  | P4             | F4  |
| P5                 | F2  | P5             | F2  |
| X                  | F1  | X              | F1  |
| I                  | A8  | I              | A8  |
| C                  | A4  | C              | A4  |
| P6                 | A2  | N              | A2  |
| P7                 | A1  | L              | A1  |
| S1                 | Z   | S1             | Z   |
| S2                 | Q   | S2             | Q   |
| L24                | N24 | W24            | W23 |
| L23                | N23 | W22            | W21 |
| L22                | N22 | W20            | W19 |
| L21                | N21 | W18            | W17 |
| L20                | N20 | W16            | W15 |
| L19                | N19 | W14            | W13 |
| L18                | N18 | W12            | W11 |
| L17                | N17 | W10            | W9  |
| L16                | N16 | W8             | W7  |
| L15                | N15 | W6             | W5  |
| L14                | N14 | W4             | W3  |
| L13                | N13 | W2             | W1  |
| L12                | N12 | R24            | R23 |
| L11                | N11 | R22            | R21 |
| L10                | N10 | R20            | R19 |
| L9                 | N9  | R18            | R17 |
| L8                 | N8  | R16            | R15 |
| L7                 | N7  | R14            | R13 |
| L6                 | N6  | R12            | R11 |
| L5                 | N5  | R10            | R9  |
| L4                 | N4  | R8             | R7  |
| L3                 | N3  | R6             | R5  |
| L2                 | N2  | R4             | R3  |
| L1                 | N1  | R2             | R1  |
| -12                | -24 | -12            | -24 |
| NC                 | -6  | NC             | -6  |
| NC                 | NC  | NC             | NC  |
| Y1                 | E   | Y1             | E   |
| 12                 | 24  | +12            | +24 |
| Y2                 | 6   | Y2             | 6   |
| 0                  | 0   | 0              | 0   |



# VME

## VersaModular Eurocard (VME):

Height →



<http://vmebusdirect.com/what-is-vme.php>

Width of VME modules: 20.3 mm

1 U rack size = 4.445 cm

### VME bus J1/P1 Pinouts

| PIN | ROW A    | ROW B    | ROW C     |
|-----|----------|----------|-----------|
| 1   | D00      | BBSY*    | D08       |
| 2   | D01      | BCLR*    | D09       |
| 3   | D02      | ACFAIL*  | D10       |
| 4   | D03      | BG0IN*   | D11       |
| 5   | D04      | BG0OUT*  | D12       |
| 6   | D05      | BG1IN*   | D13       |
| 7   | D06      | BG1OUT*  | D14       |
| 8   | D07      | BG2IN*   | D15       |
| 9   | GND      | BG2OUT*  | GND       |
| 10  | SYSCLK   | BG3IN*   | SYSFAIL*  |
| 11  | GND      | BG3OUT*  | BERR*     |
| 12  | DS1*     | BR0*     | SYSRESET* |
| 13  | DS0*     | BR1*     | LWORD*    |
| 14  | WRITE*   | BR2*     | AM5       |
| 15  | GND      | BR3*     | A23       |
| 16  | DTACK*   | AM0      | A22       |
| 17  | GND      | AM1      | A21       |
| 18  | AS*      | AM2      | A20       |
| 19  | GND      | AM3      | A19       |
| 20  | IACK*    | GND      | A18       |
| 21  | IACKIN   | SERCLK   | A17       |
| 22  | IACKOUT* | SERDAT   | A16       |
| 23  | AM4      | GND      | A15       |
| 24  | A07      | IRQ7*    | A14       |
| 25  | A06      | IRQ6*    | A13       |
| 26  | A05      | IRQ5*    | A12       |
| 27  | A04      | IRQ4*    | A11       |
| 28  | A03      | IRQ3*    | A10       |
| 29  | A02      | IRQ2*    | A09       |
| 30  | A01      | IRQ1*    | A08       |
| 31  | -12V     | +5VSTDBY | +12V      |
| 32  | +5V      | +5V      | +5V       |

### VME bus J2/P2 Pinouts

| PIN | ROW A        | ROW B    | ROW C        |
|-----|--------------|----------|--------------|
| 1   | User Defined | +5       | User Defined |
| 2   | User Defined | GND      | User Defined |
| 3   | User Defined | RESERVED | User Defined |
| 4   | User Defined | A24      | User Defined |
| 5   | User Defined | A25      | User Defined |
| 6   | User Defined | A26      | User Defined |
| 7   | User Defined | A27      | User Defined |
| 8   | User Defined | A28      | User Defined |
| 9   | User Defined | A29      | User Defined |
| 10  | User Defined | A30      | User Defined |
| 11  | User Defined | A31      | User Defined |
| 12  | User Defined | GND      | User Defined |
| 13  | User Defined | +5       | User Defined |
| 14  | User Defined | D16      | User Defined |
| 15  | User Defined | D17      | User Defined |
| 16  | User Defined | D18      | User Defined |
| 17  | User Defined | D19      | User Defined |
| 18  | User Defined | D20      | User Defined |
| 19  | User Defined | D21      | User Defined |
| 20  | User Defined | D22      | User Defined |
| 21  | User Defined | D23      | User Defined |
| 22  | User Defined | GND      | User Defined |
| 23  | User Defined | D24      | User Defined |
| 24  | User Defined | D25      | User Defined |
| 25  | User Defined | D26      | User Defined |
| 26  | User Defined | D27      | User Defined |
| 27  | User Defined | D28      | User Defined |
| 28  | User Defined | D29      | User Defined |
| 29  | User Defined | D30      | User Defined |
| 30  | User Defined | D31      | User Defined |
| 31  | User Defined | GND      | User Defined |
| 32  | User Defined | +5V      | User Defined |

### VME bus J3/P3 Pinouts

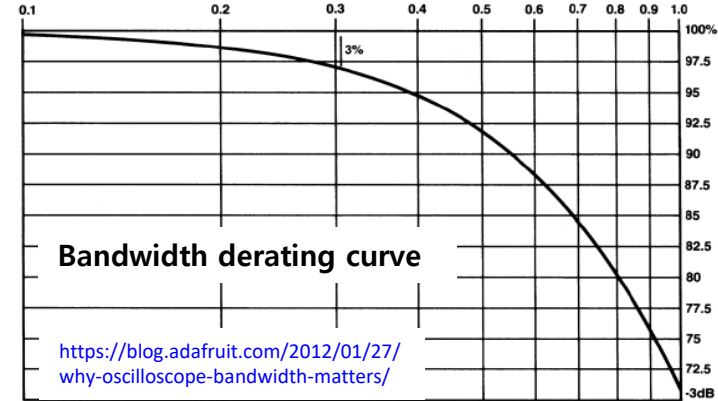
| PIN | ROW A | ROW B        | ROW C |
|-----|-------|--------------|-------|
| 1   | +5V   | User Defined | GND   |
| 2   | +5V   | User Defined | GND   |
| 3   | +5V   | User Defined | GND   |
| 4   | +5V   | User Defined | GND   |
| 5   | +5V   | User Defined | GND   |
| 6   | +5V   | User Defined | GND   |
| 7   | +5V   | User Defined | GND   |
| 8   | +5V   | User Defined | GND   |
| 9   | +5V   | User Defined | GND   |
| 10  | +5V   | User Defined | GND   |
| 11  | +5V   | User Defined | GND   |
| 12  | +5V   | User Defined | GND   |
| 13  | +5V   | User Defined | GND   |
| 14  | +5V   | User Defined | GND   |
| 15  | +5V   | User Defined | GND   |
| 16  | +5V   | User Defined | GND   |
| 17  | +5V   | User Defined | GND   |
| 18  | +5V   | User Defined | GND   |
| 19  | +5V   | User Defined | GND   |
| 20  | +5V   | User Defined | GND   |
| 21  | +5V   | User Defined | GND   |
| 22  | +5V   | User Defined | GND   |
| 23  | +5V   | User Defined | GND   |
| 24  | +5V   | User Defined | GND   |
| 25  | +5V   | User Defined | GND   |
| 26  | +12V  | User Defined | +12V  |
| 27  | +12V  | User Defined | +12V  |
| 28  | -12V  | User Defined | -12V  |
| 29  | -12V  | User Defined | -12V  |
| 30  | -5V   | User Defined | -5V   |
| 31  | -5V   | User Defined | -5V   |
| 32  | -5V   | User Defined | -5V   |

# Oscilloscope



## Bandwidth:

maximum frequency of an input signal which can pass through the analog front end of the scope with minimal amplitude loss



If you require 3% accuracy, you need to derate it by a factor of  $\sim 0.3x$ , so a **350 MHz scope can accurately measure 105 MHz to 3%**.

## Sampling rate:

maximum number of samples per second

