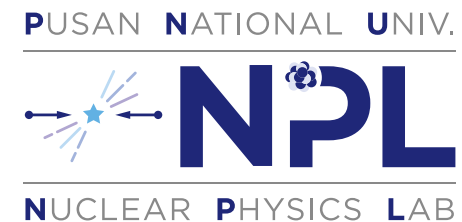


# Jet flavor tagging in $pp$ collisions using GNN for the ALICE experiment

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# Contents

0. PyTorch & GNN
1. Introduction
2. Neural network & dataset
3. Training result
4. B-jet selection optimization

Google Colab Notebook here!

[https://colab.research.google.com/drive/1pr1tb-qPGV6TnneKSxjyvq07lwkvNe2a#scrollTo=2-D-0cy9Txf &forceEdit=true&sandboxMode=true](https://colab.research.google.com/drive/1pr1tb-qPGV6TnneKSxjyvq07lwkvNe2a#scrollTo=2-D-0cy9Txf&forceEdit=true&sandboxMode=true)

Lecture notes about GNN from Stanford Univ.  
<https://web.stanford.edu/class/cs224w/>

# 0. PyTorch & GNN

- torch.nn.Module

```
class MyModule(nn.Module):  
    def __init__(self):  
        """
```

Define layer structure

```
        """
```

```
        pass
```

```
    def forward(self, x):  
        """
```

Return layer output

```
        """
```

```
        pass
```

python

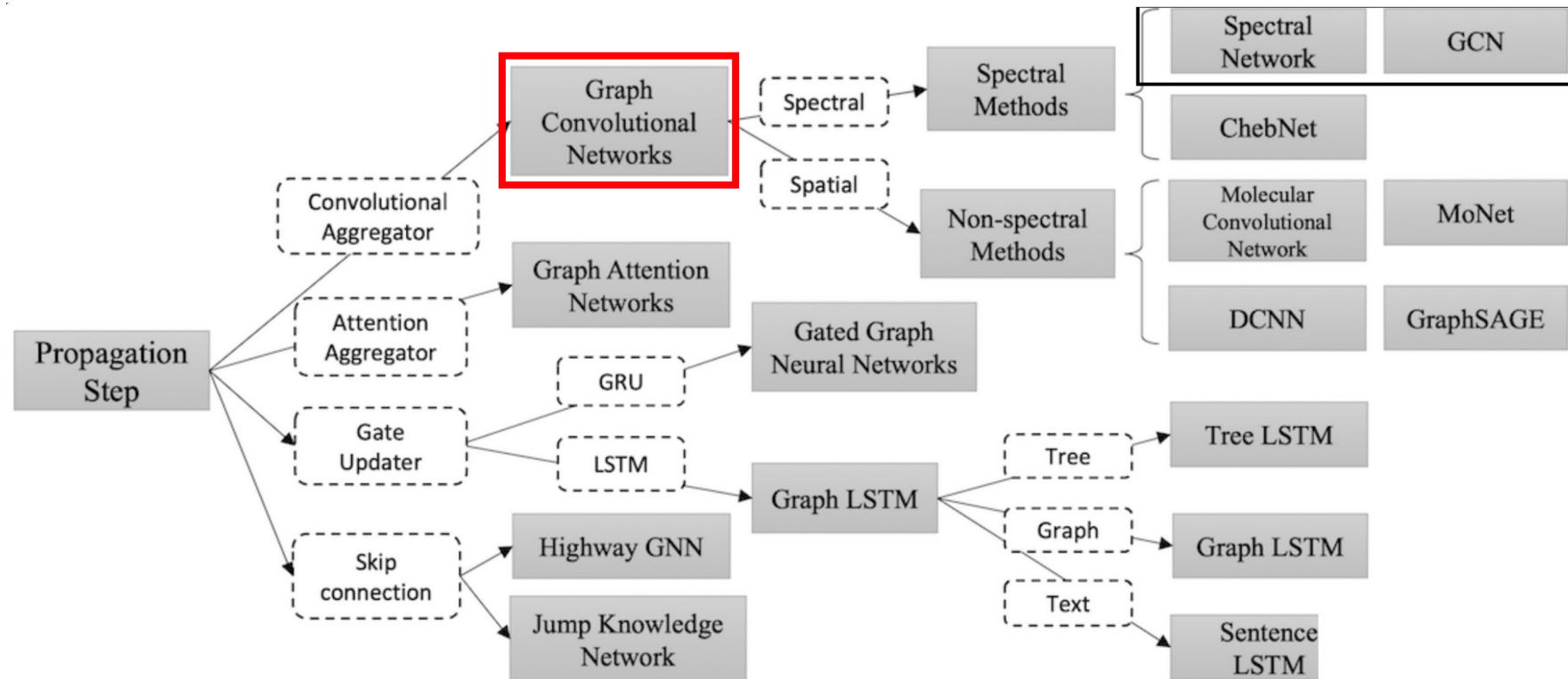
Copy code

```
import torch  
import torch.nn as nn  
import torch.nn.functional as F  
  
class GraphConvolution(nn.Module):  
    def __init__(self, in_features, out_features):  
        super(GraphConvolution, self).__init__()  
        self.linear = nn.Linear(in_features, out_features)  
  
    def forward(self, x, adj_matrix):  
        x = self.linear(x)  
        x = torch.matmul(adj_matrix, x) # 곱셈 대신에 인접 행렬과의 행렬 곱을  
        return x  
  
class GCN(nn.Module):  
    def __init__(self, input_size, hidden_size, output_size):  
        super(GCN, self).__init__()  
        self.gc1 = GraphConvolution(input_size, hidden_size)  
        self.gc2 = GraphConvolution(hidden_size, output_size)  
  
    def forward(self, x, adj_matrix):  
        x = F.relu(self.gc1(x, adj_matrix))  
        x = self.gc2(x, adj_matrix)  
        return F.log_softmax(x, dim=1)
```

# 0. PyTorch & GNN

- GNN

Many kinds of GNNs there are...



# 1. Introduction

Jet flavor tagging

Traditional methods

Neural networks

# 1. Introduction

- Jet flavor tagging

: Identifying which flavor (**bottom**, **charm** or **light flavor**) of parton is responsible for the jet production.

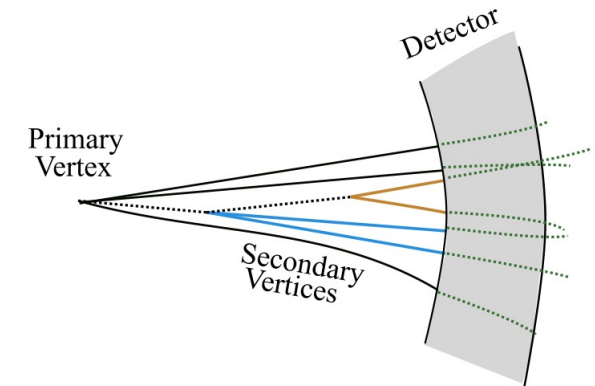
(light = u, d, s quark & gluon)

Physical phenomena vary **depending on the flavor of quark**.

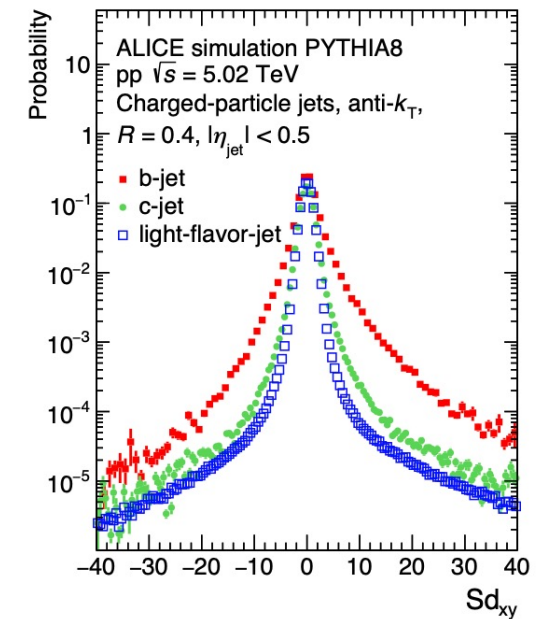
e.g. dead cone effect, longer lifetime of heavy-flavor hadrons

These can be studied through observables such as

DCA(track impact parameter), secondary vertices, momenta, the number of jet constituents, etc..



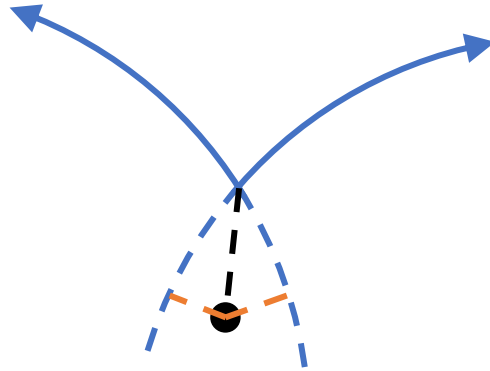
J. Shlomi et al., *Eur.Phys.J.C* (2021) 81:540



ALICE Collaboration, *JHEP* 01 (2022) 178

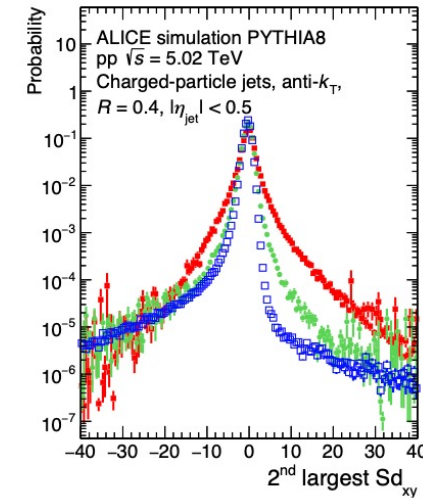
# 1. Introduction

- Traditional methods
  - IP (Impact parameter)

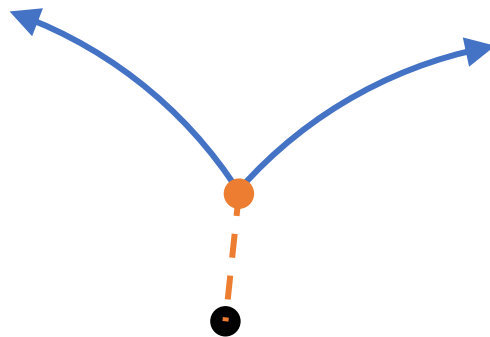


$$Sd_{xy} > Sd_{xy}^{\min}$$

→ b-jet candidate



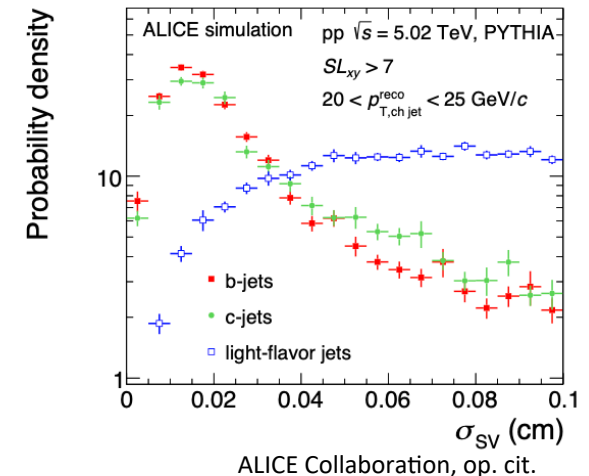
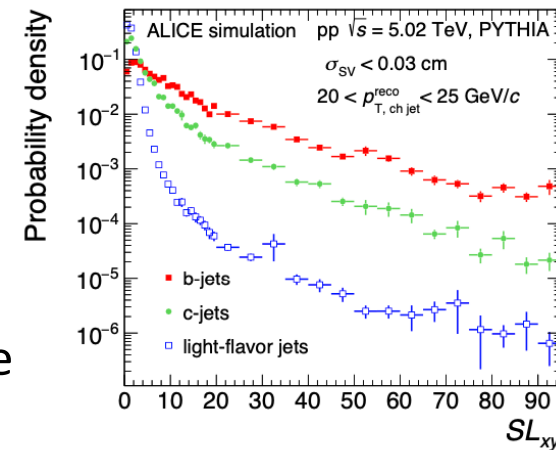
- SV (Secondary vertex)



$$SL_{xy} > SL_{xy}^{\min}$$

$$\sigma_{SV} < \sigma_{SV}^{\max}$$

→ b-jet candidate



# 1. Introduction

- Neural network

: Many recent studies [using NN for jet flavor tagging](#) are ongoing, and they show improved performances compared to previous methods.

Many different types of neural networks

: DNN, GNN, RNN, CNN(image), ...

In this research...

→ Secondary vertex finding using [Set2Graph NN](#),  
and jet flavor tagging using [Graph Neural Networks \(GNN\)](#)

(Reference: J. Shlomi et al., *Eur.Phys.J.C* (2021) 81:540)

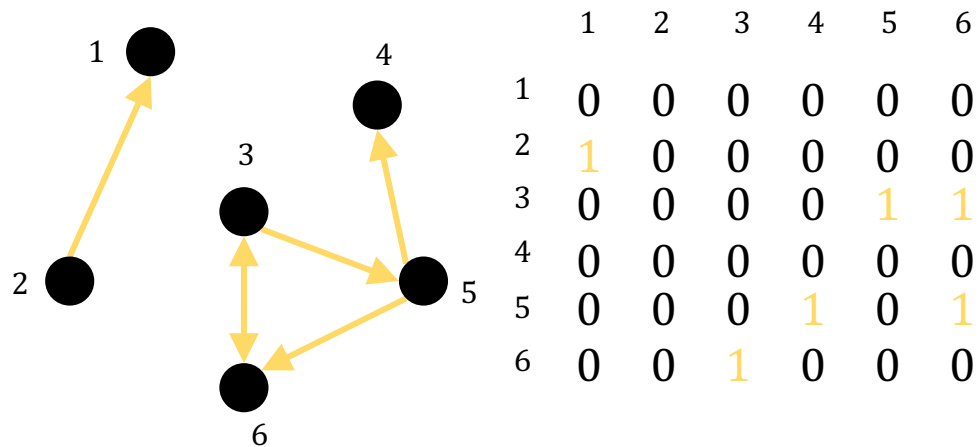


# 1. Introduction

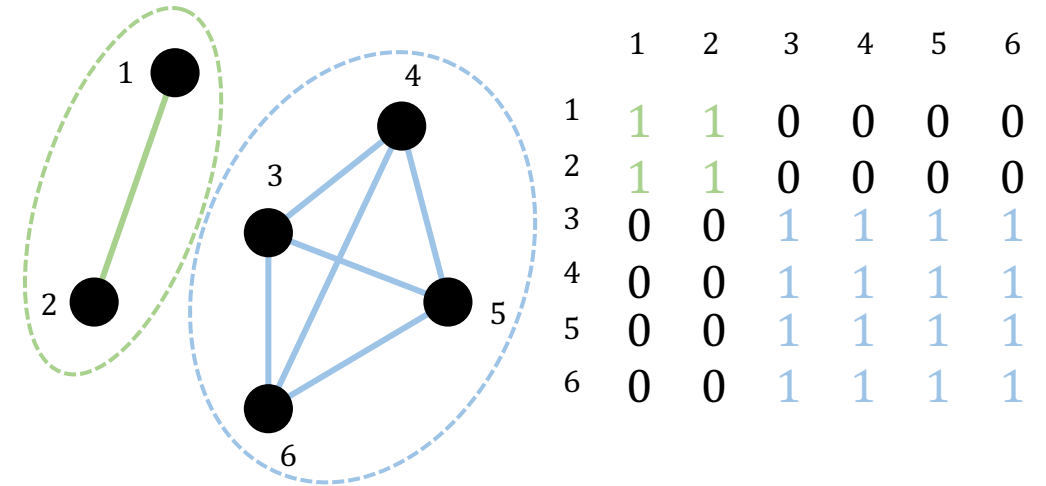
- Graph (discrete mathematics)

: Sets of **Nodes** connected by **Edges**.

In this research, **A Graph** represents **A single Jet**, **Nodes** correspond to **Tracks**(jet constituents), and **Edges** correspond to **Connections between tracks** originating from **same vertex**.



▲ directed graph representation



▲ cluster graph representation

# 2. Neural network & dataset

Neural network structure

Vertex finding (Set2Graph NN)

Jet flavor tagging (GNN)

Dataset specification

# 2. Neural network & dataset

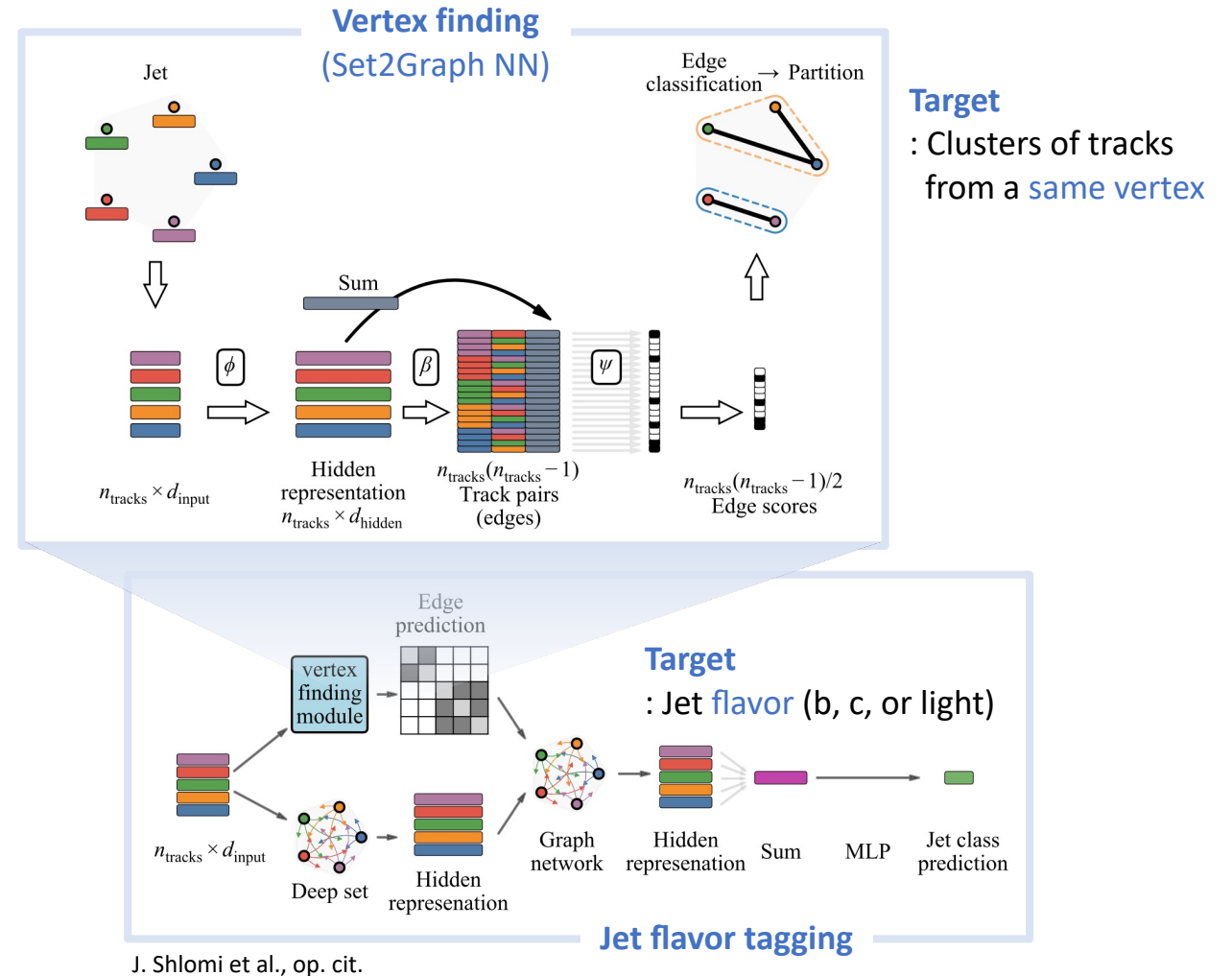
- Neural network structure

- Vertex finding : Set2Graph NN

→ Grouping of tracks originating from a common (primary or secondary) vertex

- Jet flavor tagging : GNN that takes hidden representations of tracks and vertex prediction by vertex finding module as input.

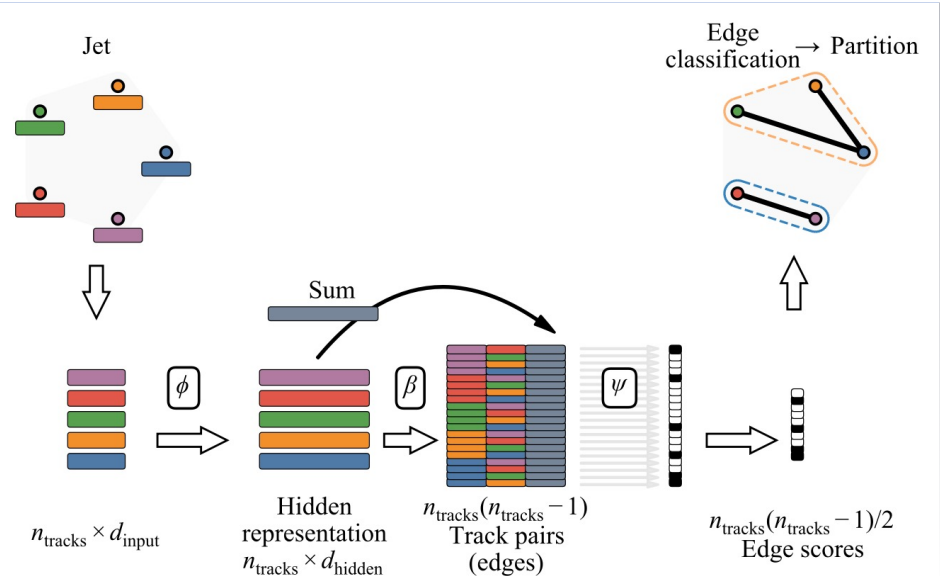
→ Jet flavor (b, c, or light jet)



# 2. Neural network & dataset

- Vertex finding  
: Set2Graph NN

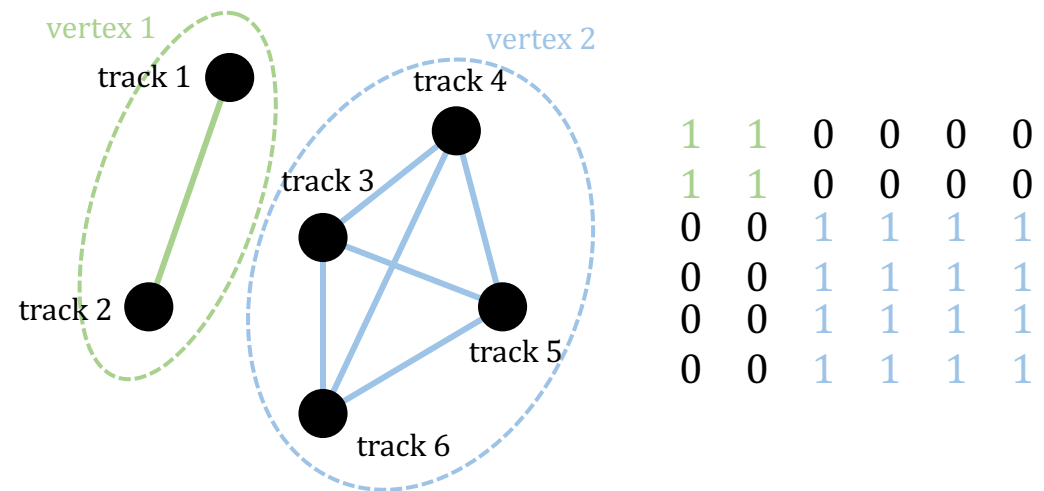
Input: **Set** of constituent tracks  
 → Output: **Graph** connecting tracks originating from a common vertex.



$\phi$ : set-to-set component  
 → Deep sets network

$\beta$ : broadcasting layer  
 → Node representations to edge representations  
 (Pairs of track  $i$  and track  $j$ )

$\psi$ : final edge classifier  
 → Edge prediction (MLP)



▲ Matrix representation of an example output

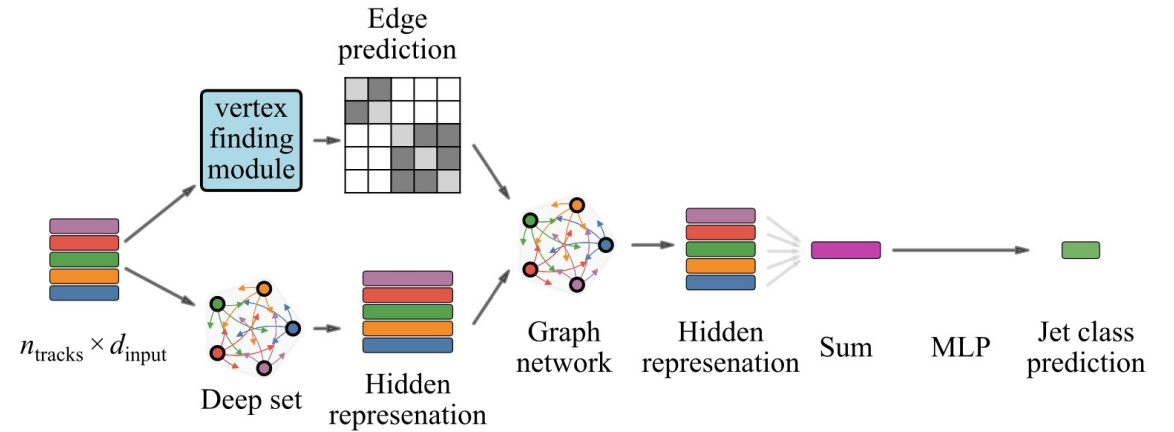
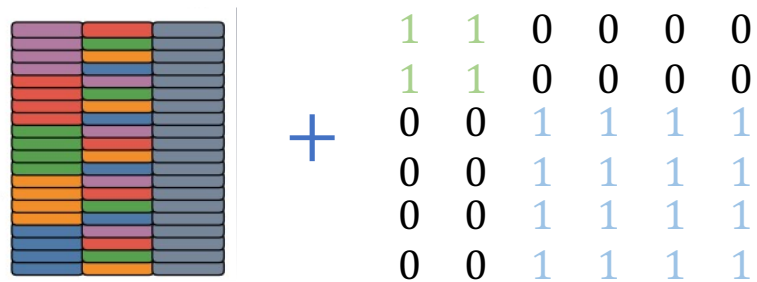
# 2. Neural network & dataset

- Jet flavor tagging  
: GNN that takes **vertex prediction result** of vertex finding module as input.

GNN (Graph Neural Networks)

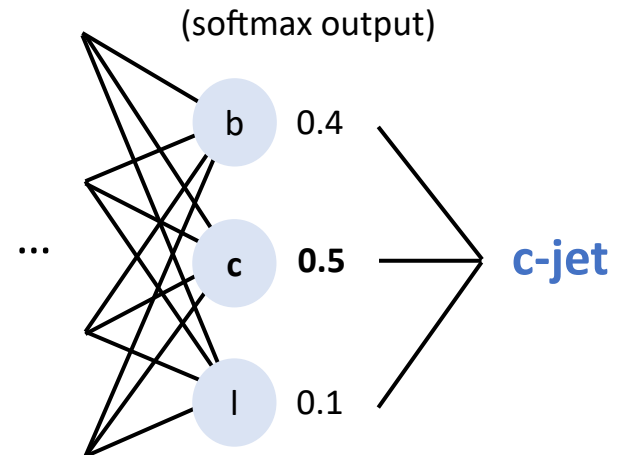
Input

: **Graph** consisting of **Nodes**(features of tracks and a jet) and **Edge prediction** by the vertex finding module



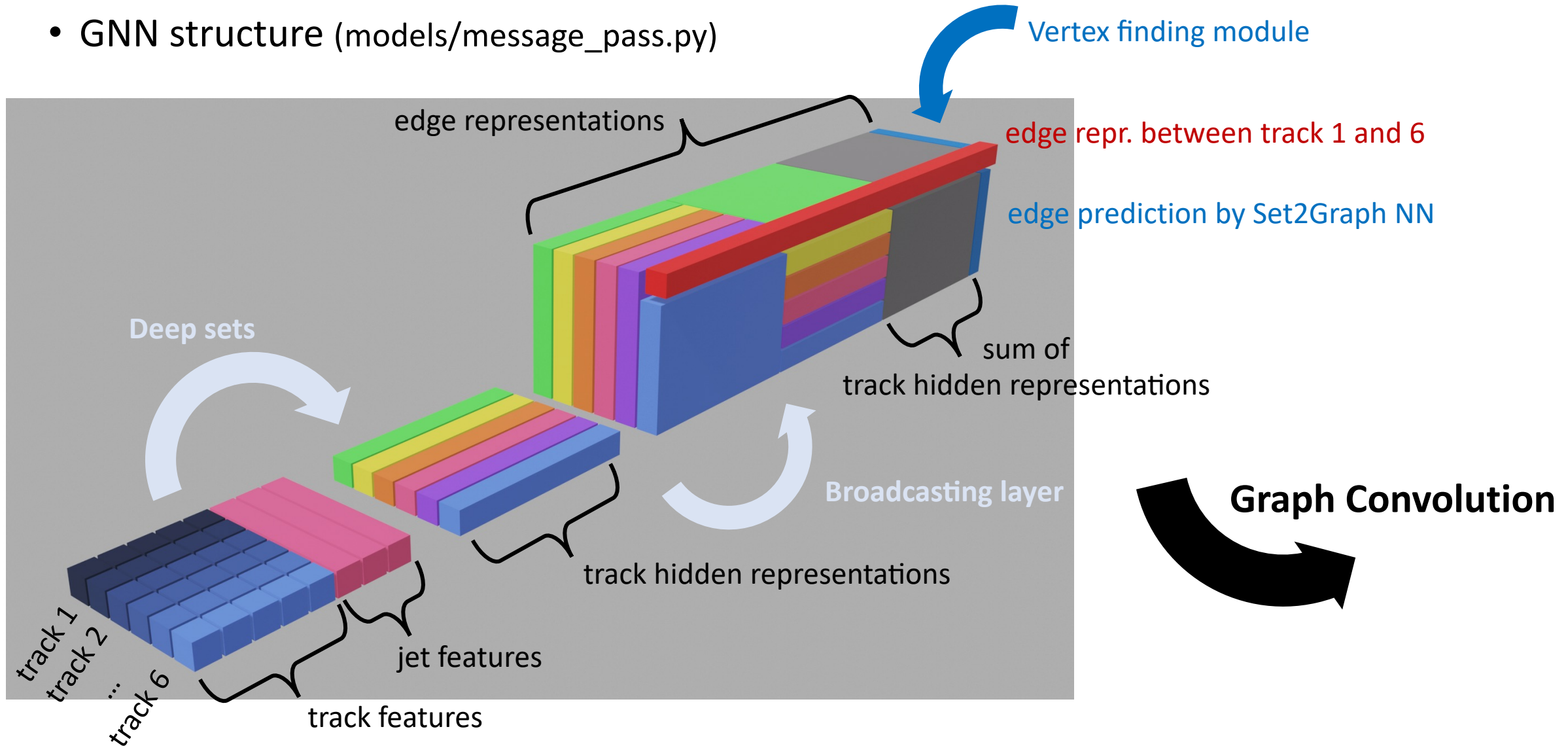
Output

: The **flavor** of the jet (b, c, or light jet)



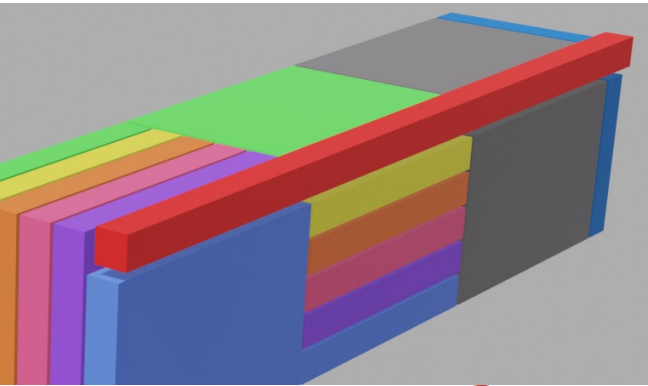
# 2. Neural network & dataset

- GNN structure (models/message\_pass.py)

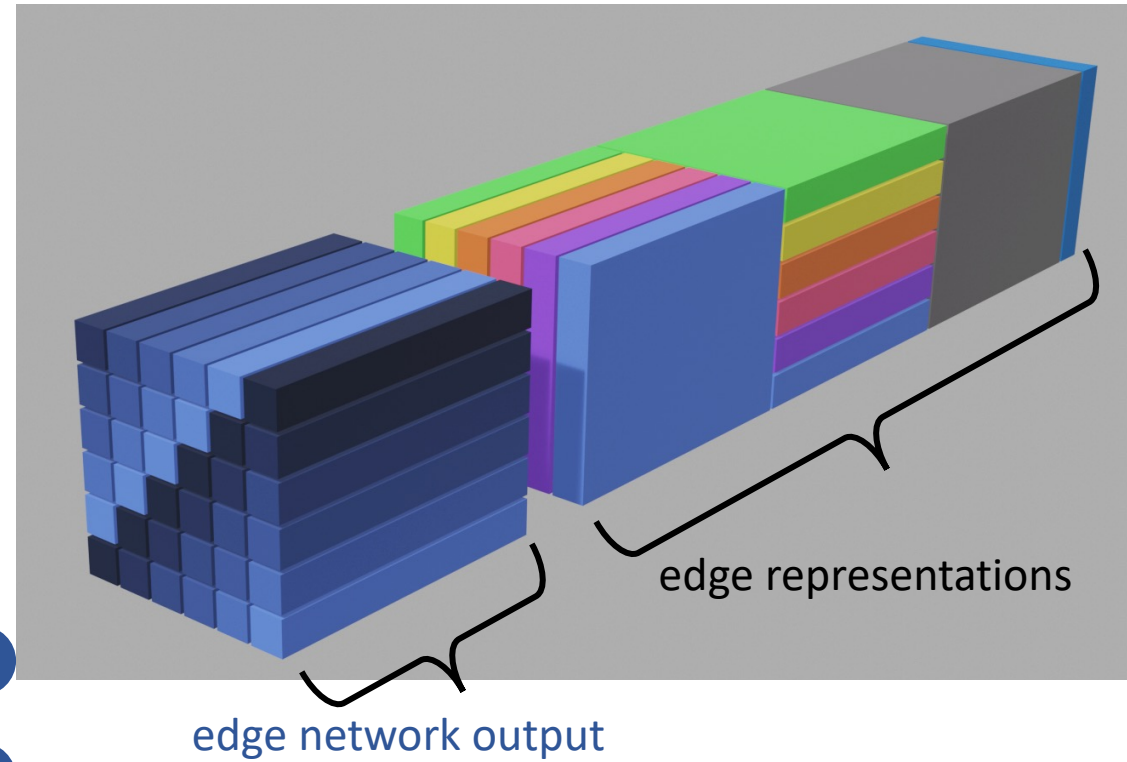
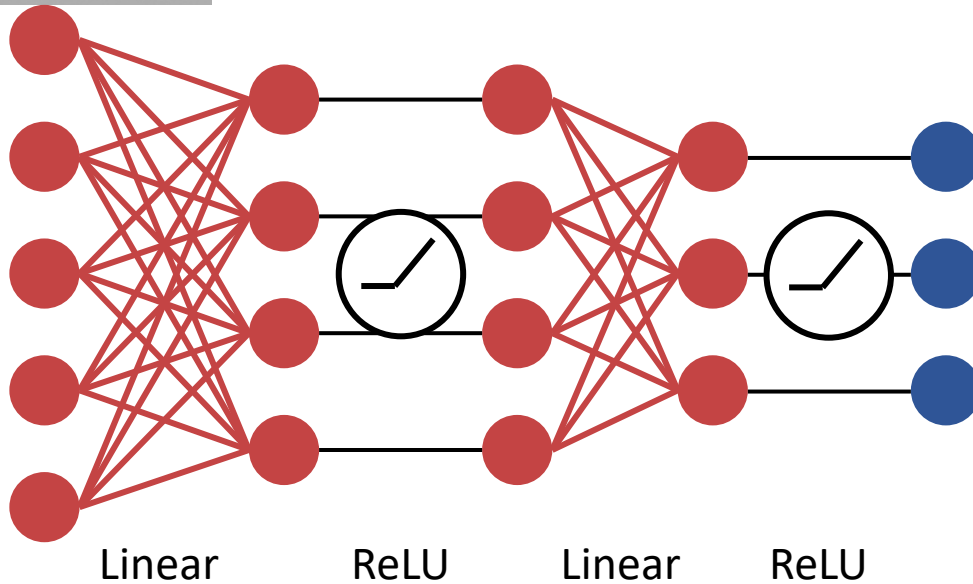


# 2. Neural network & dataset

- GNN structure (models/message\_pass.py)



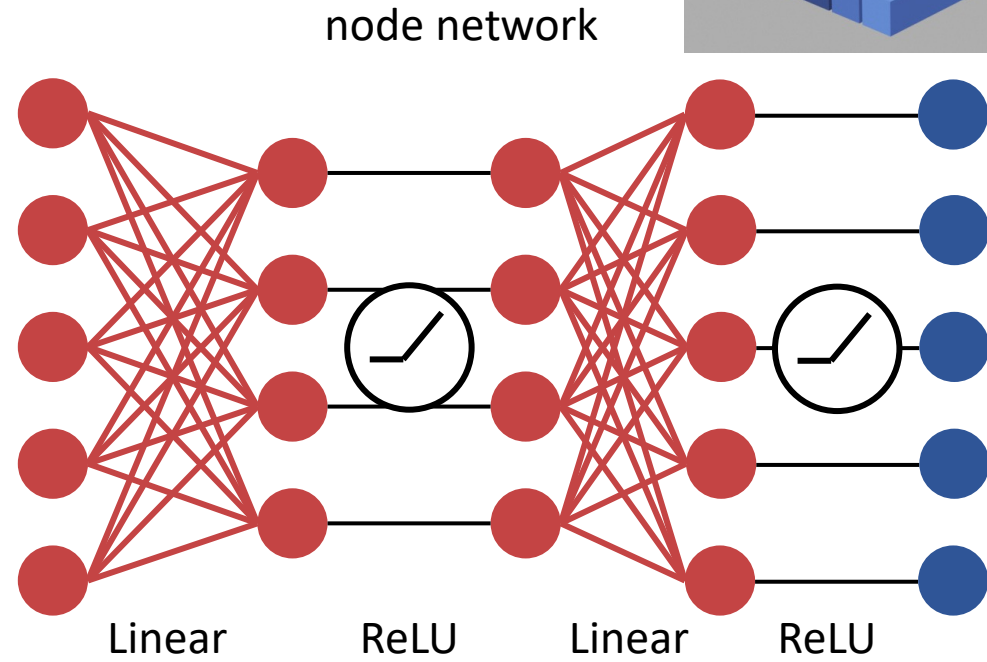
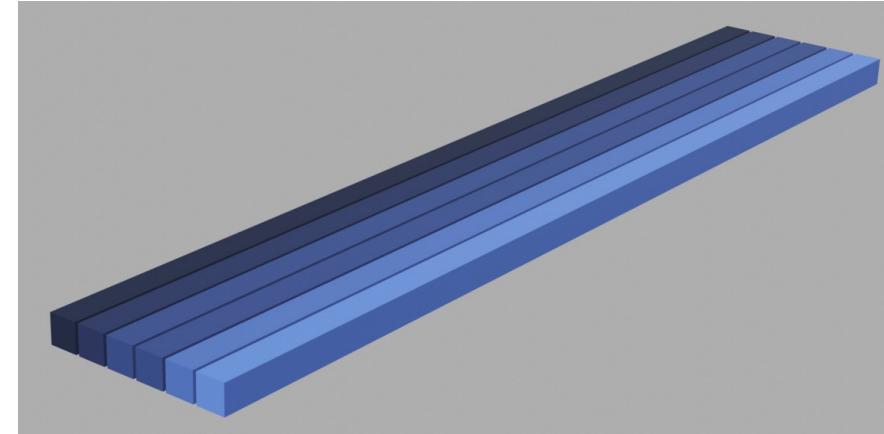
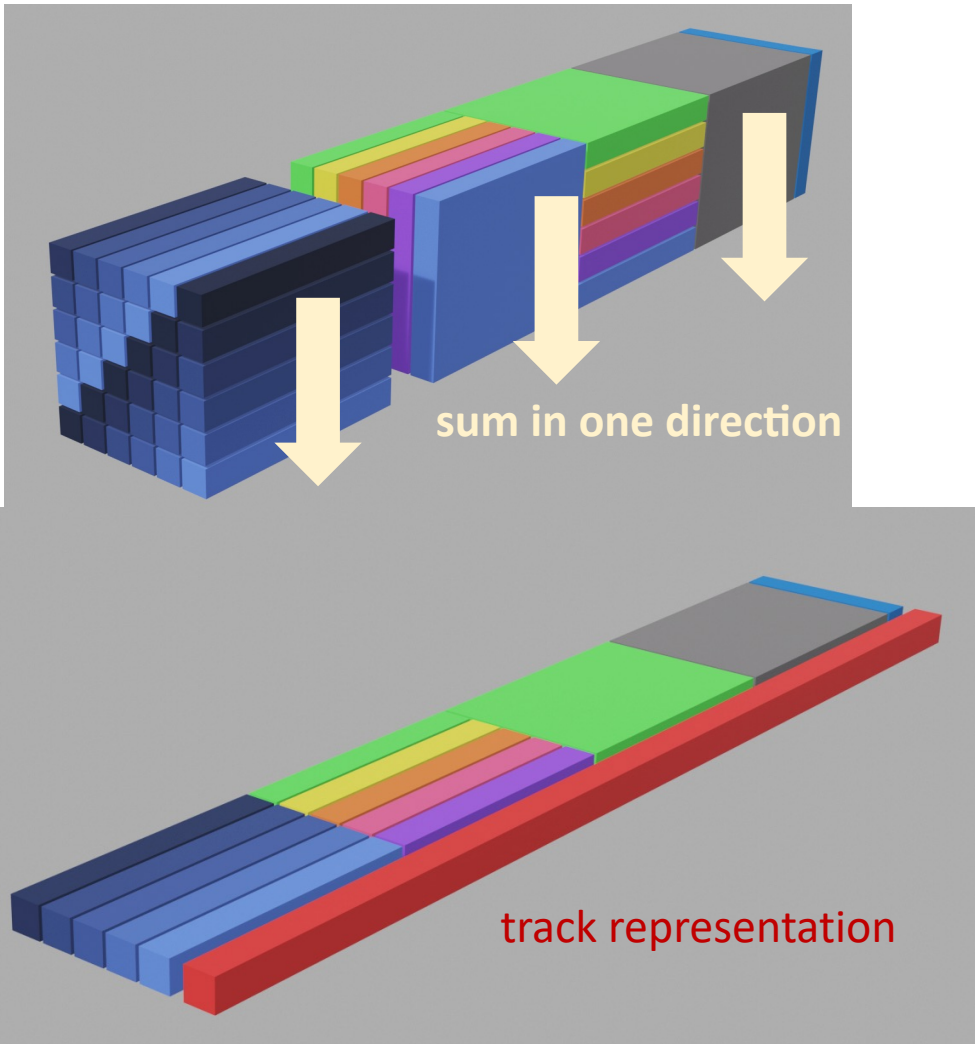
edge network





# 2. Neural network & dataset

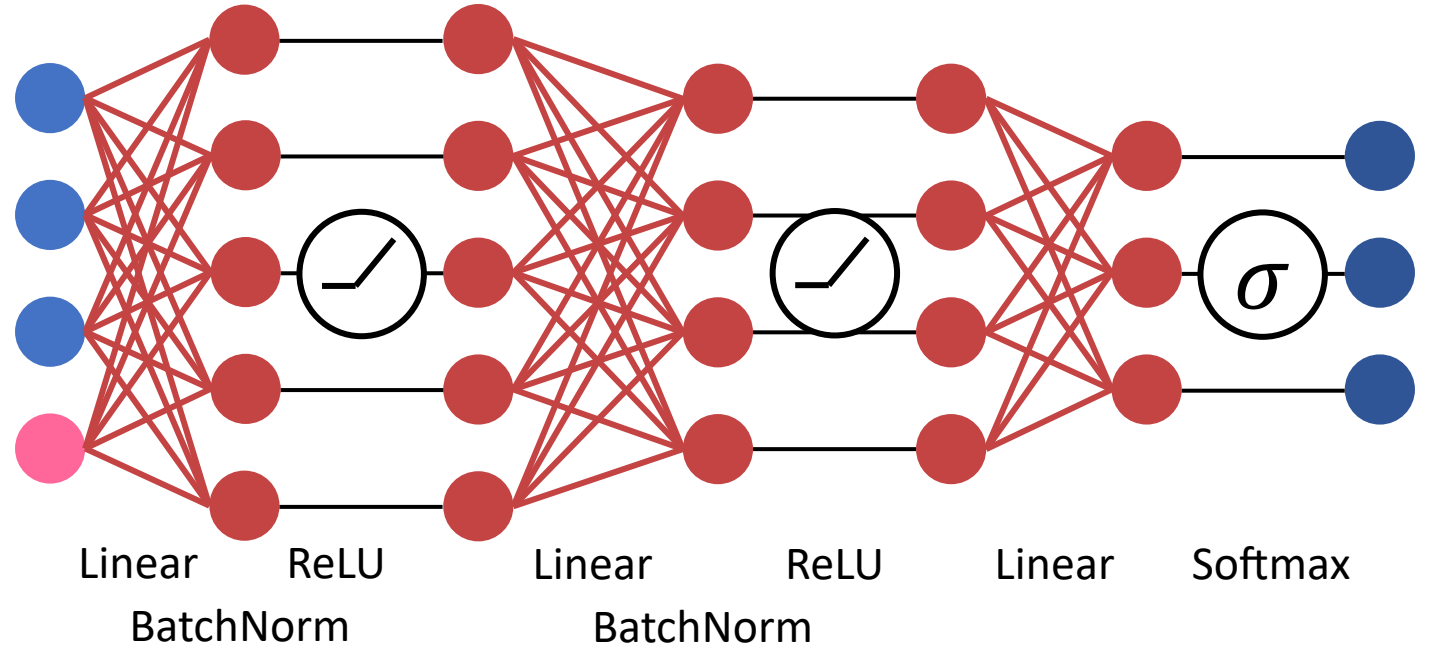
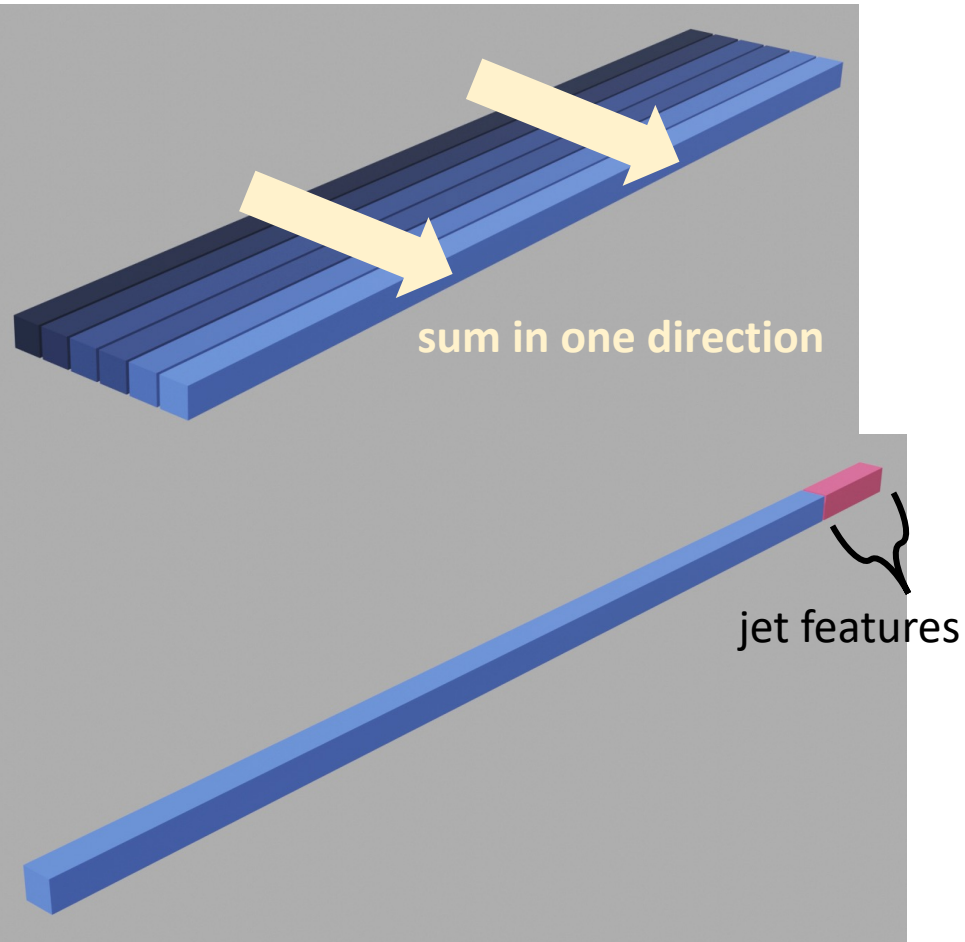
- GNN structure (models/message\_pass.py)





# 2. Neural network & dataset

- GNN structure (models/message\_pass.py)



softmax  $\rightarrow$  argmax  $\rightarrow$  jet flavor!

# 2. Neural network & dataset

- Training procedure

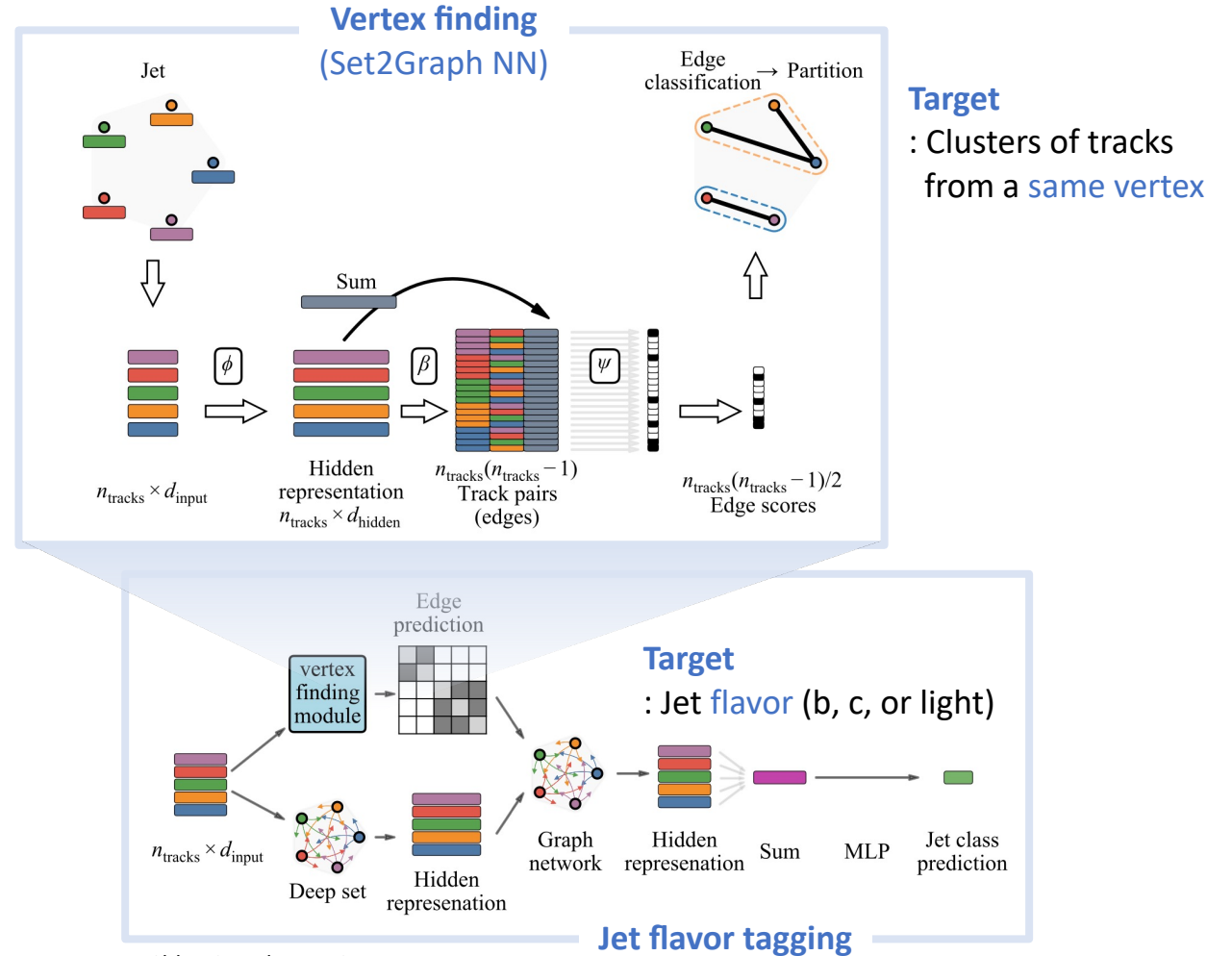
(1) Training (supervised learning) the **vertex finding module** with MC truth vertex information.

Batch size: 2048  
 Optimizer: Adam ( $\text{lr} = 10^{-3}$ )  
 Loss function: BCE and  $F_{\beta}^*$   
 Early stopping: 20 epochs

(2) Training **jet flavor tagging neural networks** (including trained vertex finding module inside).

Batch size: 1000  
 Optimizer: Adam ( $\text{lr} = 5 \times 10^{-4}$ )  
 Loss function: Cross entropy  
 Early stopping: 20 epochs

\* It is also possible to omit procedure (1).



# 2. Neural network & dataset

- Dataset specification

## ALICE Run2 MC data

- PYTHIA  $pp$  collision,  $\sqrt{s} = 5.02 \text{ TeV}$ ,  $b\bar{b}$  (LHC18k6a),  $c\bar{c}$  (LHC18k6b), jet-jet (LHC18b8) events
- ALICE (Run2) full simulation

## Jets

- Anti- $k_T$  ( $R = 0.4$ ), charged particle jets
- $10 < p_{T, \text{jet}} < 100 \text{ GeV}/c$
- $|\eta_{\text{jet}}| < 0.5$
- $2 \leq n_{\text{tracks}} (\leq 16)$

## Dataset size

- Training **500 k jets**, validation **100 k jets**, test **100 k jets** (smaller dataset will be used for hands-on.)
- Dataset contains almost **same numbers of b/c/light jets**.

# 2. Neural network & dataset

- Input properties

### Jet properties

:  $p_{T, jet}, \eta_{jet}, \phi_{jet}, m_{jet}$

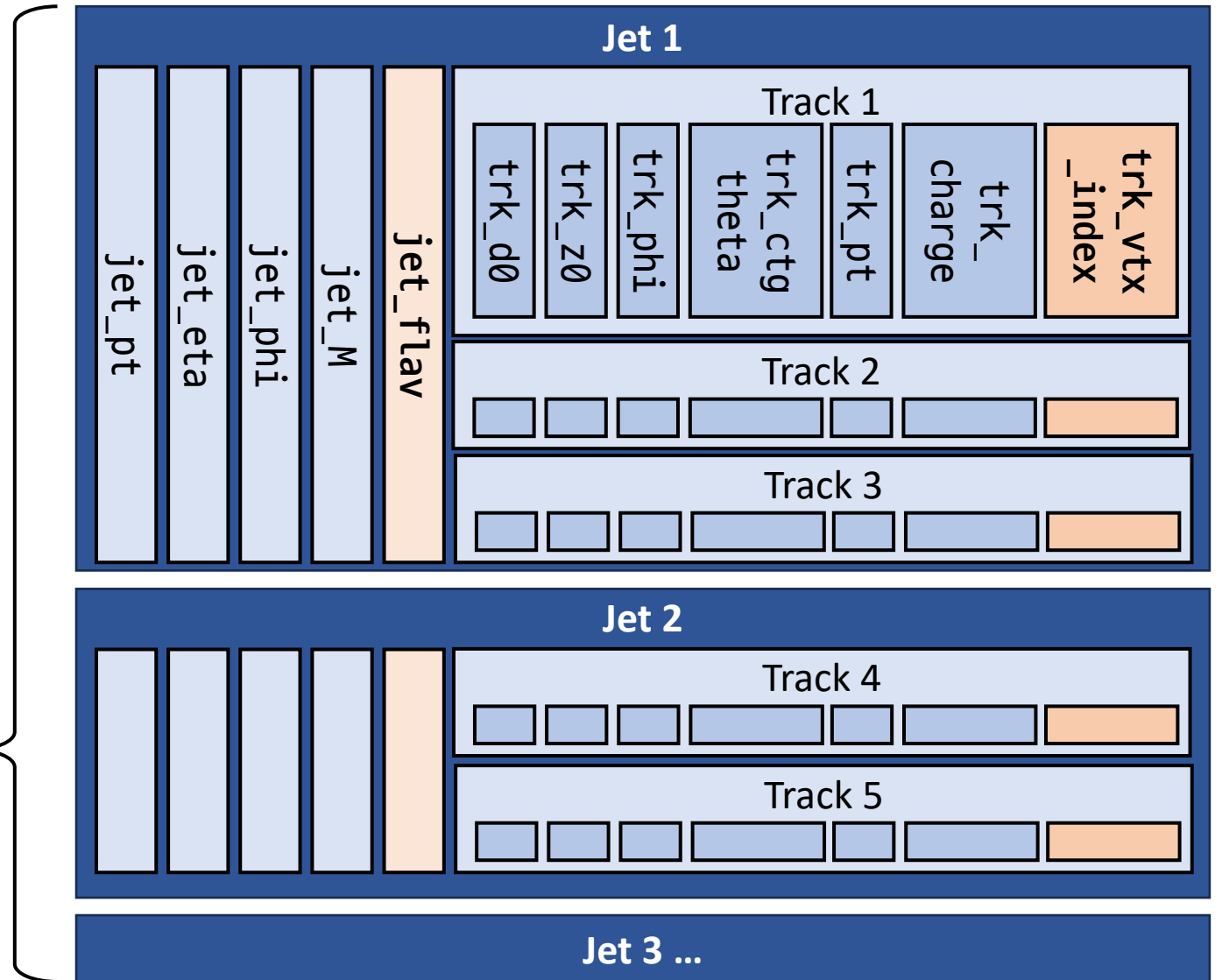
### (reconstructed) Track properties

:  $DCA_{xy}, DCA_z, p_T, \cot \theta, \phi, q$

■ Input data

■ Label data (=correct answer)

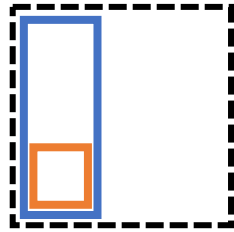
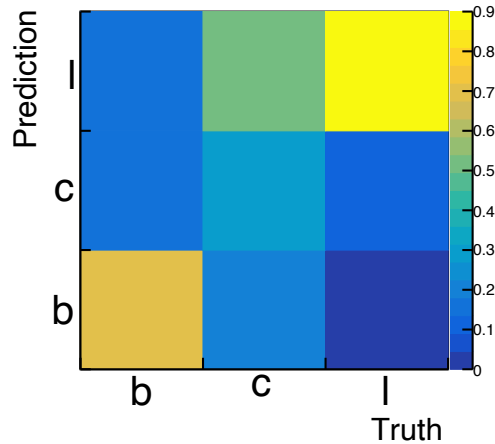
Dataset



# 3. Training result

# 3. Training result

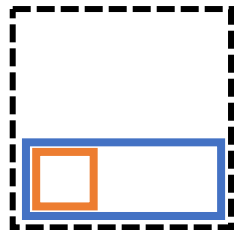
- Performance metrics



- Efficiency( $x$ ) =  $\frac{(\text{truth} = x \wedge \text{pred} = x)}{(\text{truth} = x)}$

→ How many **truth x** are found?

(Independent to the numbers of truth b/c/light jets)

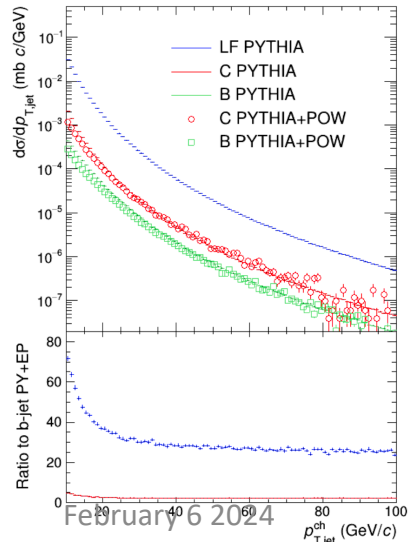


- Purity( $x$ ) =  $\frac{(\text{truth} = x \wedge \text{pred} = x)}{(\text{pred} = x)} = \frac{\epsilon_b N_b}{\epsilon_b N_b + \epsilon_{c \rightarrow b} N_c + \epsilon_{l \rightarrow b} N_l}$

( $\epsilon_b$ : b-jet efficiency,  $\epsilon_{x \rightarrow b}$ : fraction of mis-tagged truth x-jets among b-jet candidates)

→ How many of **predicted x** are true?

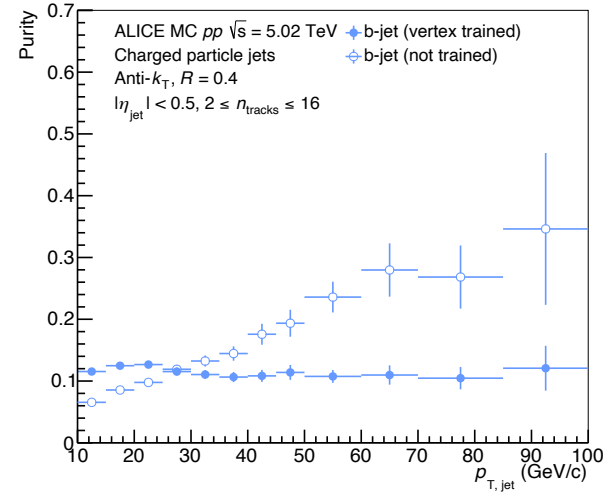
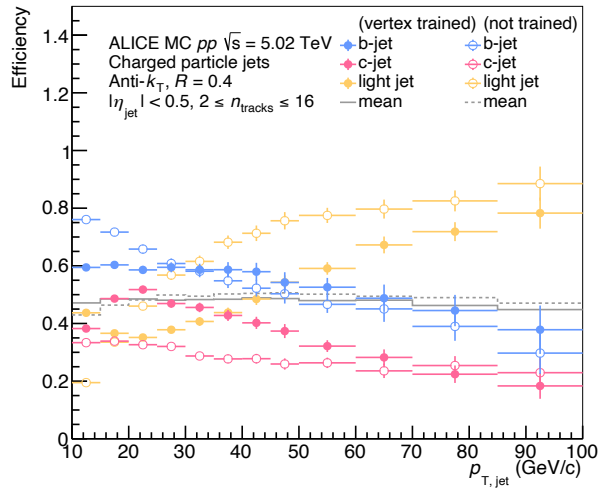
(Dependent to the numbers of truth b/c/light jets)



\*Purity is calculated on the assumption that jet cross-section ratio as constant **b : c : l = 1 : 2 : 27**. (in temporary)

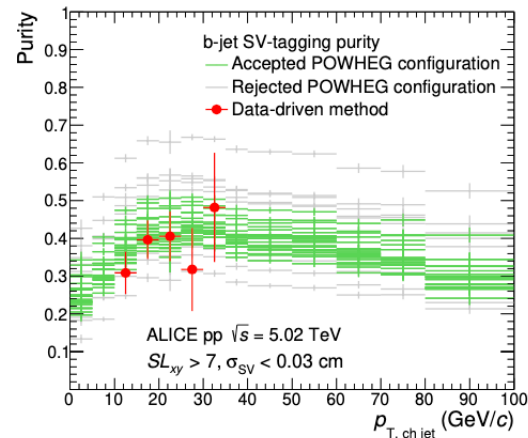
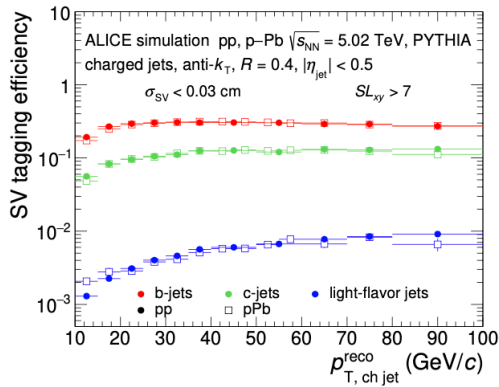
# 3. Training result

- Performance



- B-jet efficiency is **higher**, purity is **lower** than previous SV method.
- Efficiency and purity are **complementary**, so both should be considered at the same time.

## SV method (ALICE)



→ The **optimization** of working point is needed to get **higher purity b-jet** result.

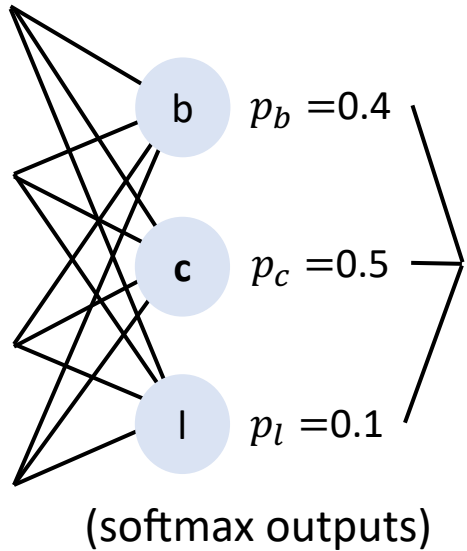
ALICE Collaboration, op.cit.

# 4. B-jet selection optimization



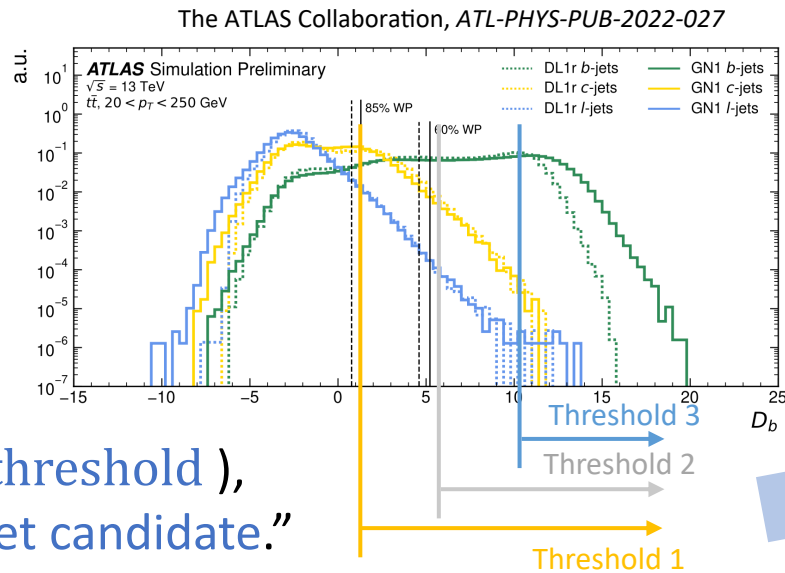
# 4. B-jet selection optimization

- B-jet tagging discriminant

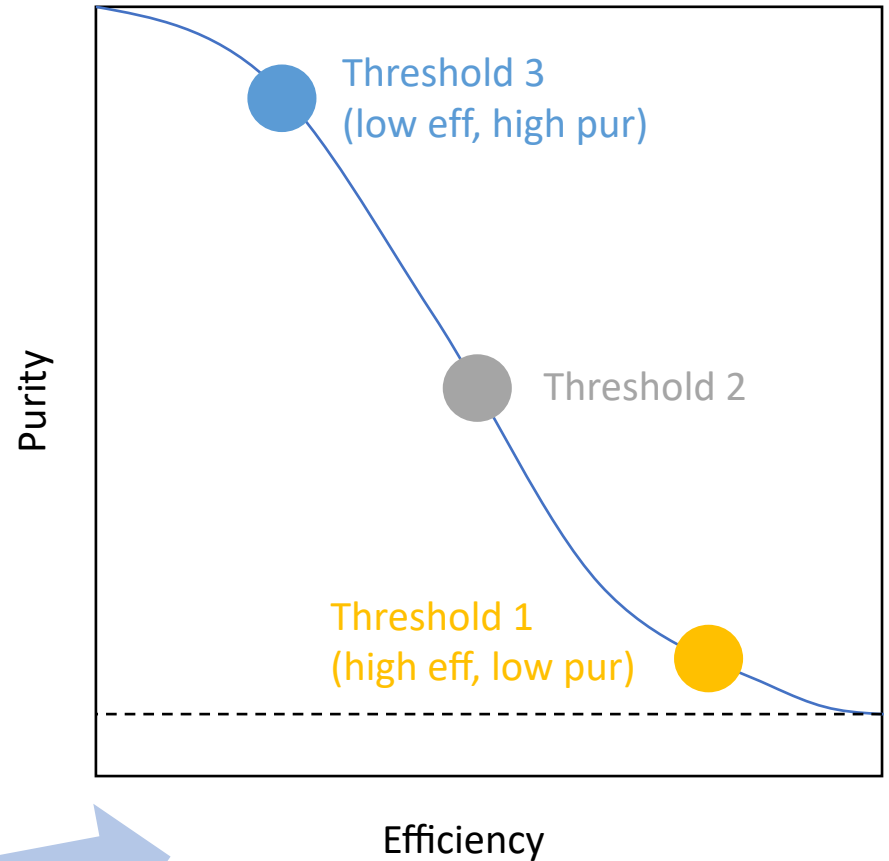


$$D_b = \log \frac{p_b}{(1 - f_c)p_l + f_c p_c}$$

( $f_c = 0.018$ , optimized parameter)



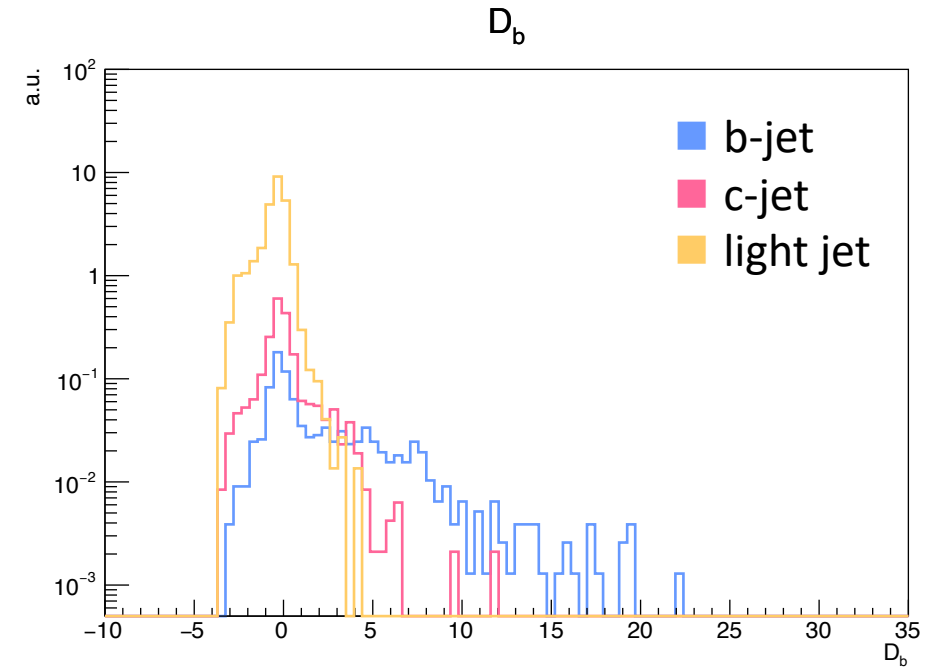
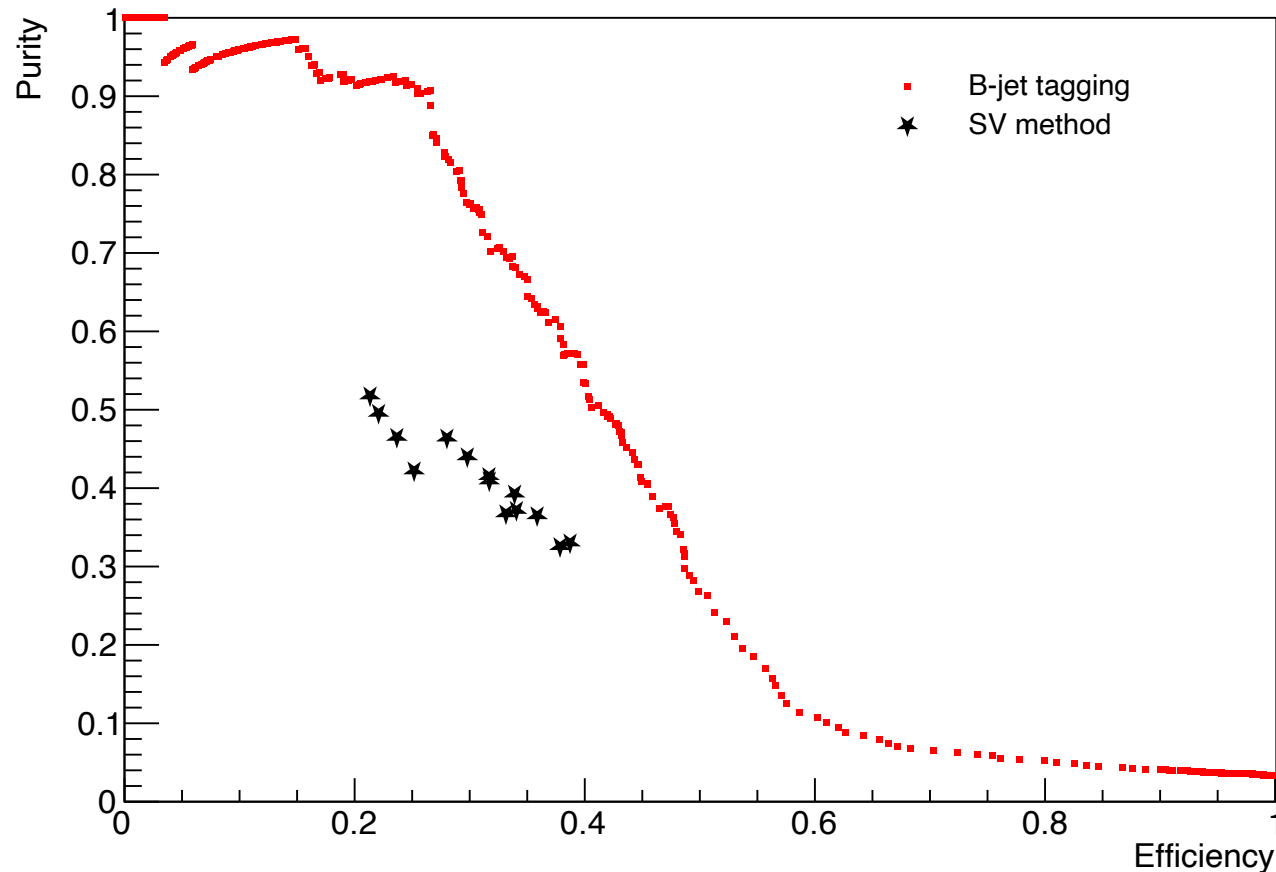
“if ( $D_b > \text{threshold}$ ),  
 then it is a b-jet candidate.”



# 4. B-jet selection optimization

- Efficiency and purity

(for the range  $p_{T, \text{jet}} = 50 \sim 60 \text{ GeV}/c$ )

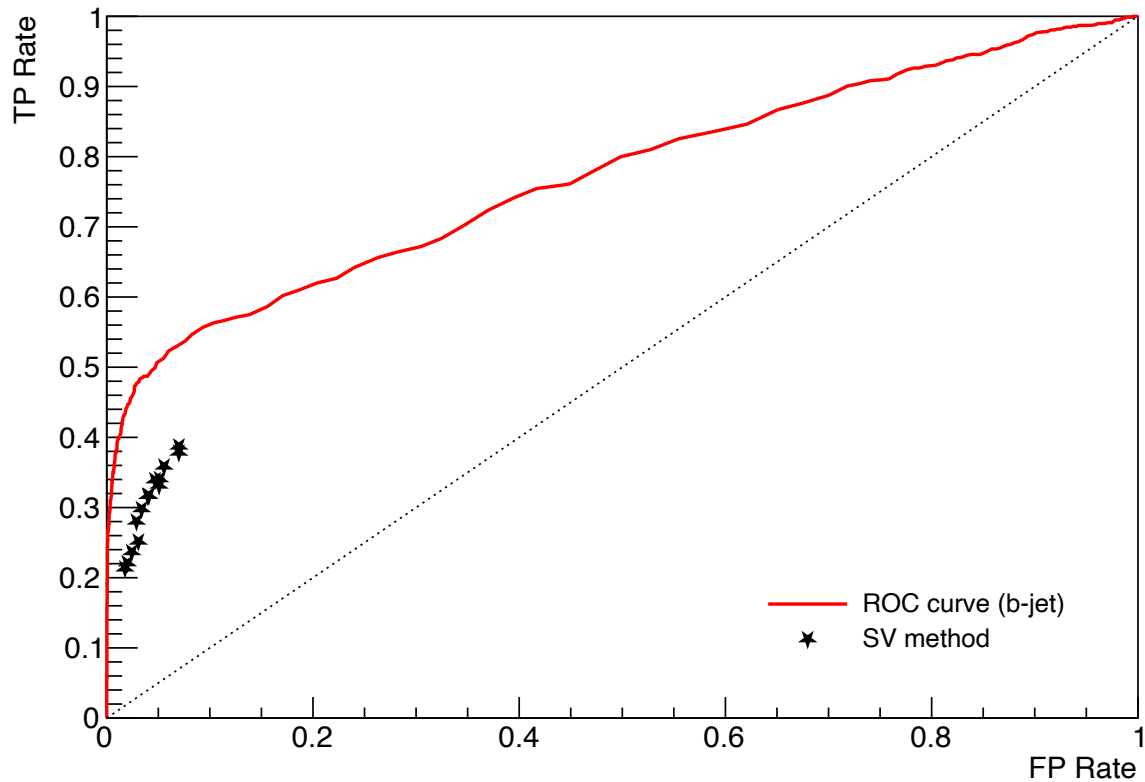


- Both efficiency and purity are higher than SV method at high purity region.

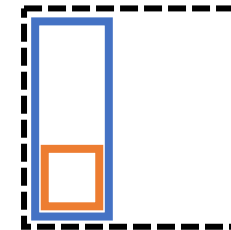
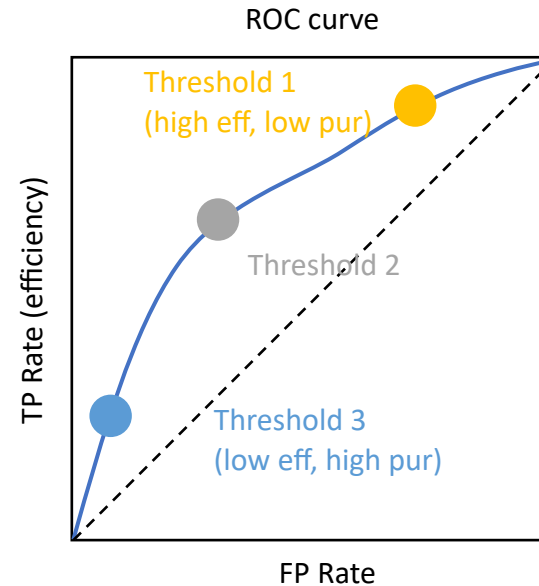
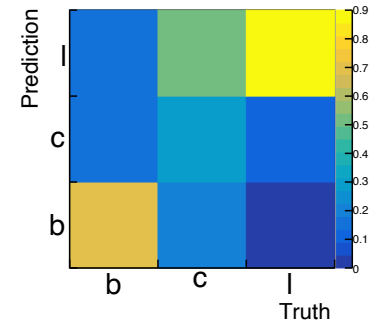
# 4. B-jet selection optimization

- ROC (Receiver Operating Characteristic) curve  
(for the range  $p_{T, \text{jet}} = 50 \sim 60 \text{ GeV}/c$ )

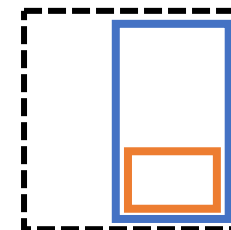
ROC curve



- AUC (Area Under Curve)  
: 0.773



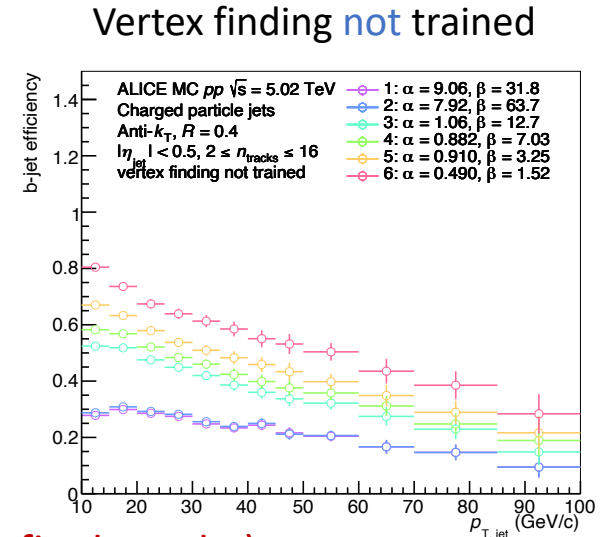
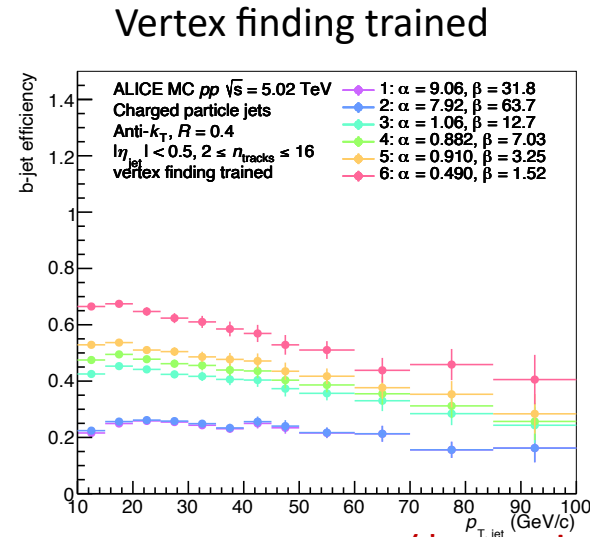
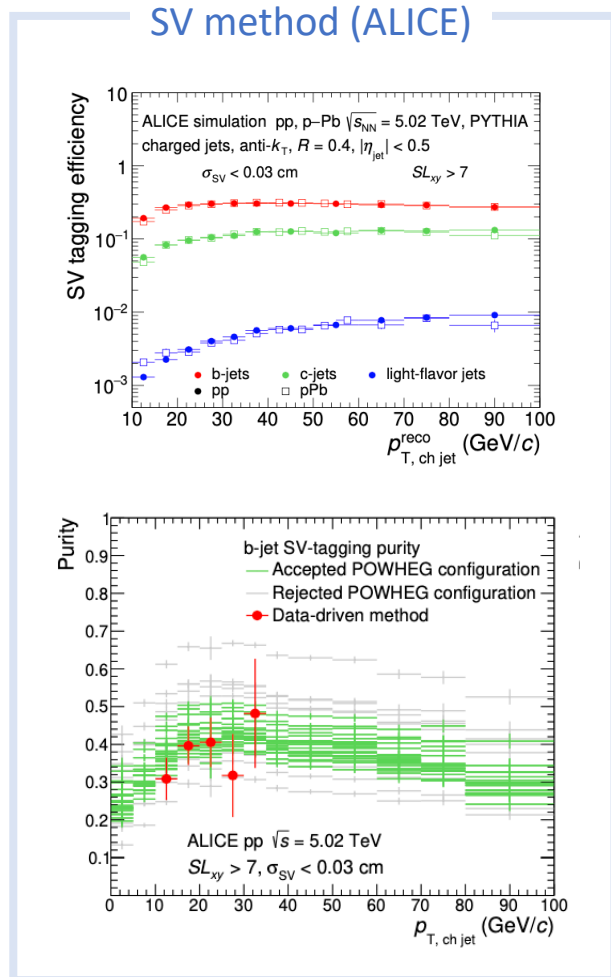
$$\text{TP rate} = \frac{(\text{truth} = x \wedge \text{pred} = x)}{(\text{truth} = x)}$$



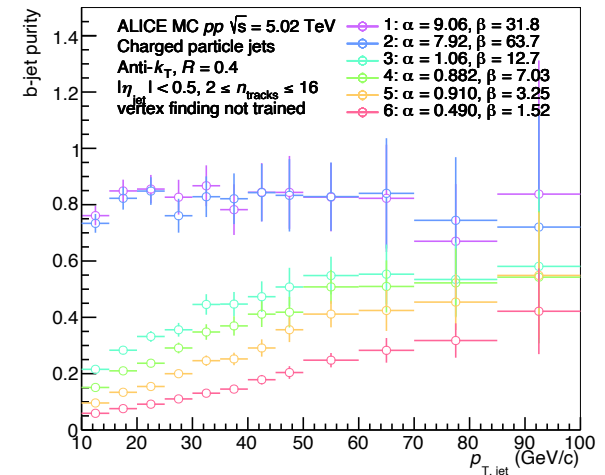
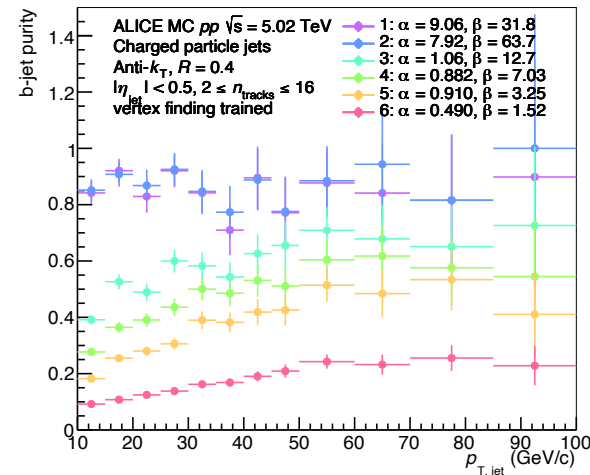
$$\text{FP rate} = \frac{(\text{truth} \neq x \wedge \text{pred} = x)}{(\text{truth} \neq x)}$$

# 4. B-jet selection optimization

- High purity working points



(\* Not the final results)



# Thank you

## References

- [1] J. Shlomi et al, *Eur.Phys.J.C* (2021) 81:540.
- [2] ALICE Collaboration, *JHEP* 01 (2022) 178.
- [3] The ATLAS Collaboration, ATL-PHYS-PUB-2022-027.